

# Today

- **Linking**
  - Motivation
  - How it works
  - Dynamic linking
- **Case study: Library interpositioning**

# Example C Program

```
int sum(int *a, int n);

int array[2] = {1, 2};

int main(int argc, char** argv)
{
    int val = sum(array, 2);
    return val;
}
```

*main.c*

```
int sum(int *a, int n)
{
    int i, s = 0;

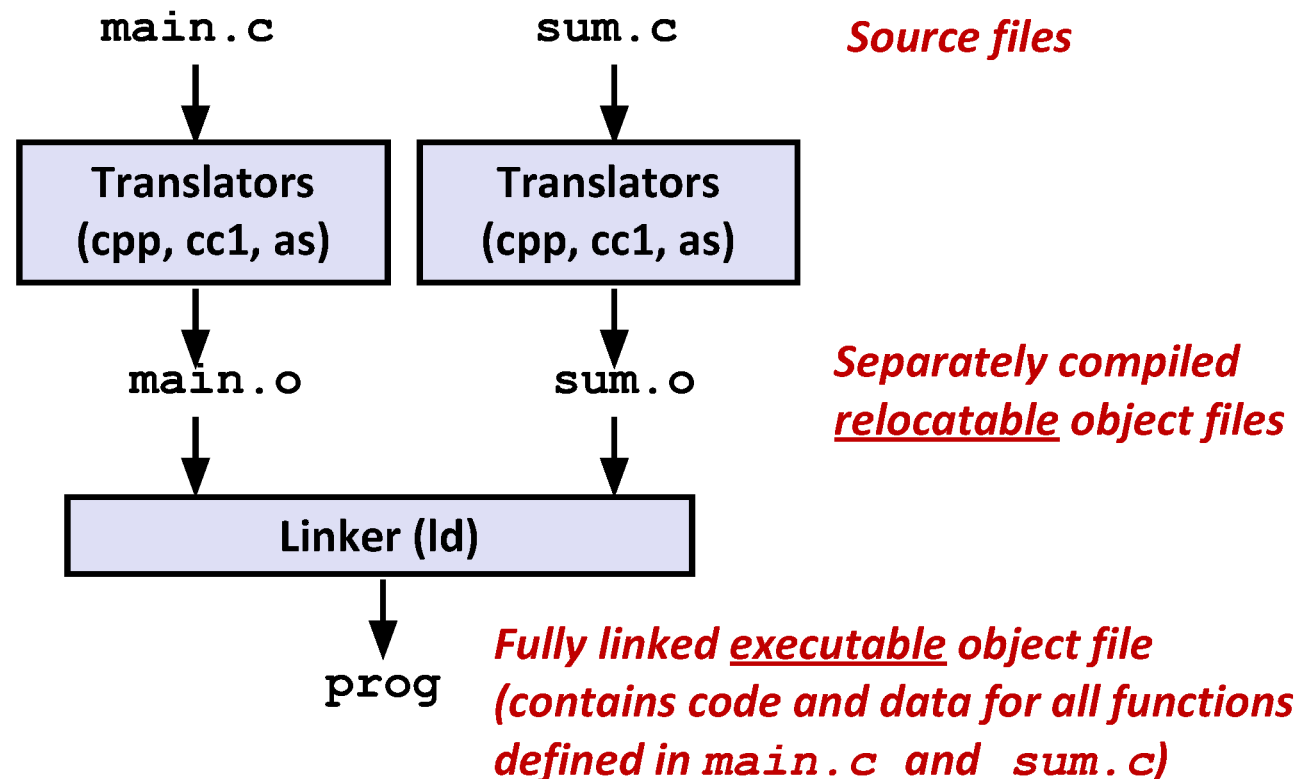
    for (i = 0; i < n; i++) {
        s += a[i];
    }
    return s;
}
```

*sum.c*

# Linking

- Programs are translated and linked using a *compiler driver*:

- `linux> gcc -Og -o prog main.c sum.c`
- `linux> ./prog`



# Why Linkers?

## ■ Reason 1: Modularity

- Program can be written as a collection of smaller source files, rather than one monolithic mass.
- Can build libraries of common functions (more on this later)
  - e.g., Math library, standard C library

# Why Linkers? (cont)

## ■ Reason 2: Efficiency

- Time: Separate compilation
  - Change one source file, compile, and then relink.
  - No need to recompile other source files.
  - Can compile multiple files concurrently.
- Space: Libraries
  - Common functions can be aggregated into a single file...
  - **Option 1: *Static Linking***
    - Executable files and running memory images contain only the library code they actually use
  - **Option 2: *Dynamic linking***
    - Executable files contain no library code
    - During execution, single copy of library code can be shared across all executing processes

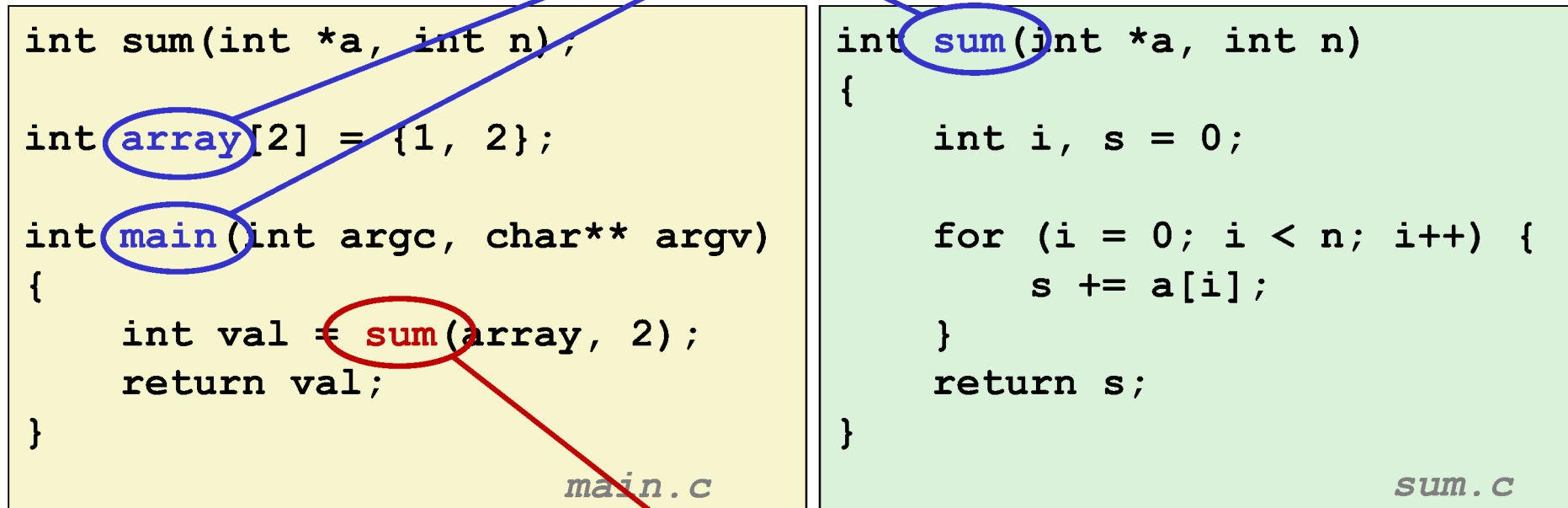
# What Do Linkers Do?

## ■ Step 1: Symbol resolution

- Programs define and reference *symbols* (global variables and functions):
  - `void swap() {...} /* define symbol swap */`
  - `swap(); /* reference symbol swap */`
  - `int *xp = &x; /* define symbol xp, reference x */`
- Symbol definitions are stored in object file (by assembler) in *symbol table*.
  - Symbol table is an array of entries
  - Each entry includes name, size, and location of symbol.
- **During symbol resolution step, the linker associates each symbol reference with exactly one symbol definition.**

# Symbols in Example C Program

## Definitions



## Reference

# What Do Linkers Do? (cont)

## ■ Step 2: Relocation

- Merges separate code and data sections into single sections
- Relocates symbols from their relative locations in the `.o` files to their final absolute memory locations in the executable.
- Updates all references to these symbols to reflect their new positions.

**Let's look at these two steps in more detail....**



# Three Kinds of Object Files (Modules)

## ■ Relocatable object file (.o file)

- Contains code and data in a form that can be combined with other relocatable object files to form executable object file.
  - Each .o file is produced from exactly one source (.c) file

## ■ Executable object file (a.out file)

- Contains code and data in a form that can be copied directly into memory and then executed.

## ■ Shared object file (.so file)

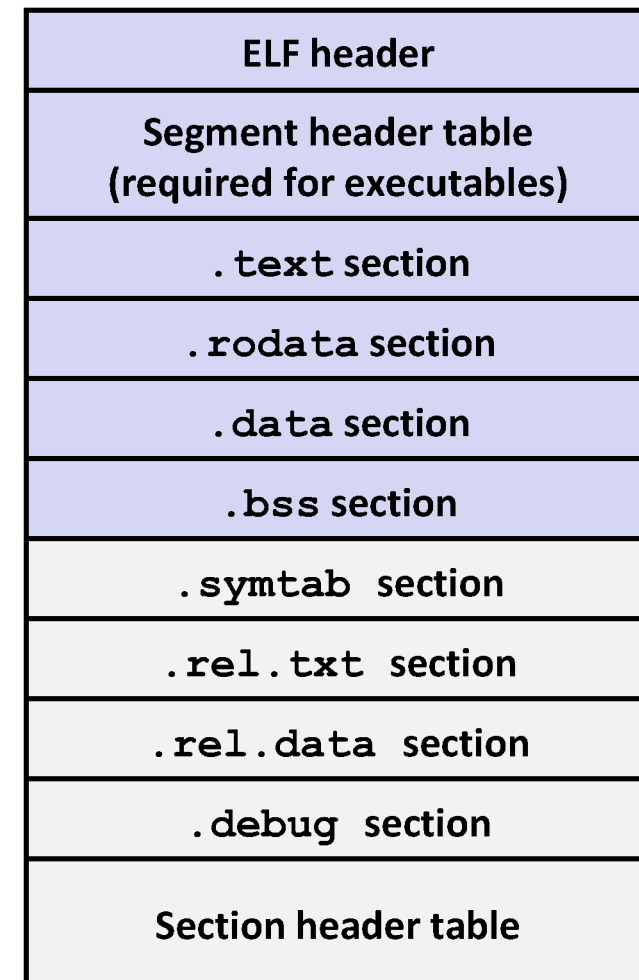
- Special type of relocatable object file that can be loaded into memory and linked dynamically, at either load time or run-time.
- Called *Dynamic Link Libraries* (DLLs) by Windows

# Executable and Linkable Format (ELF)

- **Standard binary format for object files**
  
- **One unified format for**
  - Relocatable object files (`.o`),
  - Executable object files (`a.out`)
  - Shared object files (`.so`)
  
- **Generic name: ELF binaries**

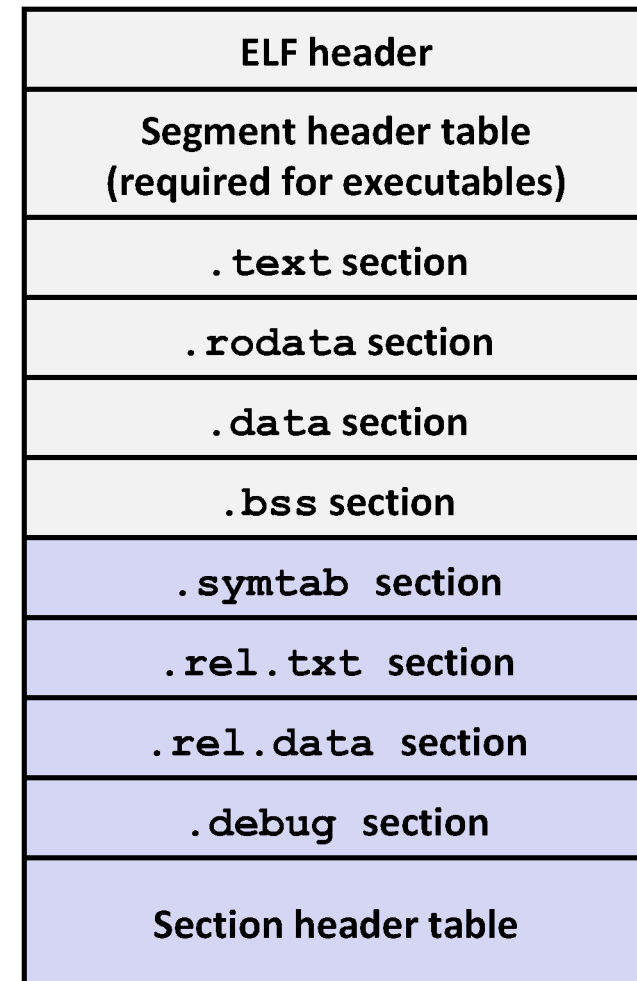
# ELF Object File Format

- **Elf header**
  - Word size, byte ordering, file type (.o, exec, .so), machine type, etc.
- **Segment header table**
  - Page size, virtual addresses memory segments (sections), segment sizes.
- **.text section**
  - Code
- **.rodata section**
  - Read only data: jump tables, ...
- **.data section**
  - Initialized global variables
- **.bss section**
  - Uninitialized global variables
  - “Block Started by Symbol”
  - **“Better Save Space”**



# ELF Object File Format (cont.)

- **.symtab section**
  - Symbol table
  - Procedure and static variable names
  - Section names and locations
- **.rel.text section**
  - Relocation info for **.text** section
  - Addresses of instructions that will need to be modified in the executable
  - Instructions for modifying.
- **.rel.data section**
  - Relocation info for **.data** section
  - Addresses of pointer data that will need to be modified in the merged executable
- **.debug section**
  - Info for symbolic debugging (`gcc -g`)
- **Section header table**
  - Offsets and sizes of each section



# Linker Symbols

## ■ Global symbols

- Symbols defined by module  $m$  that can be referenced by other modules.
- E.g.: non-`static` C functions and non-`static` global variables.

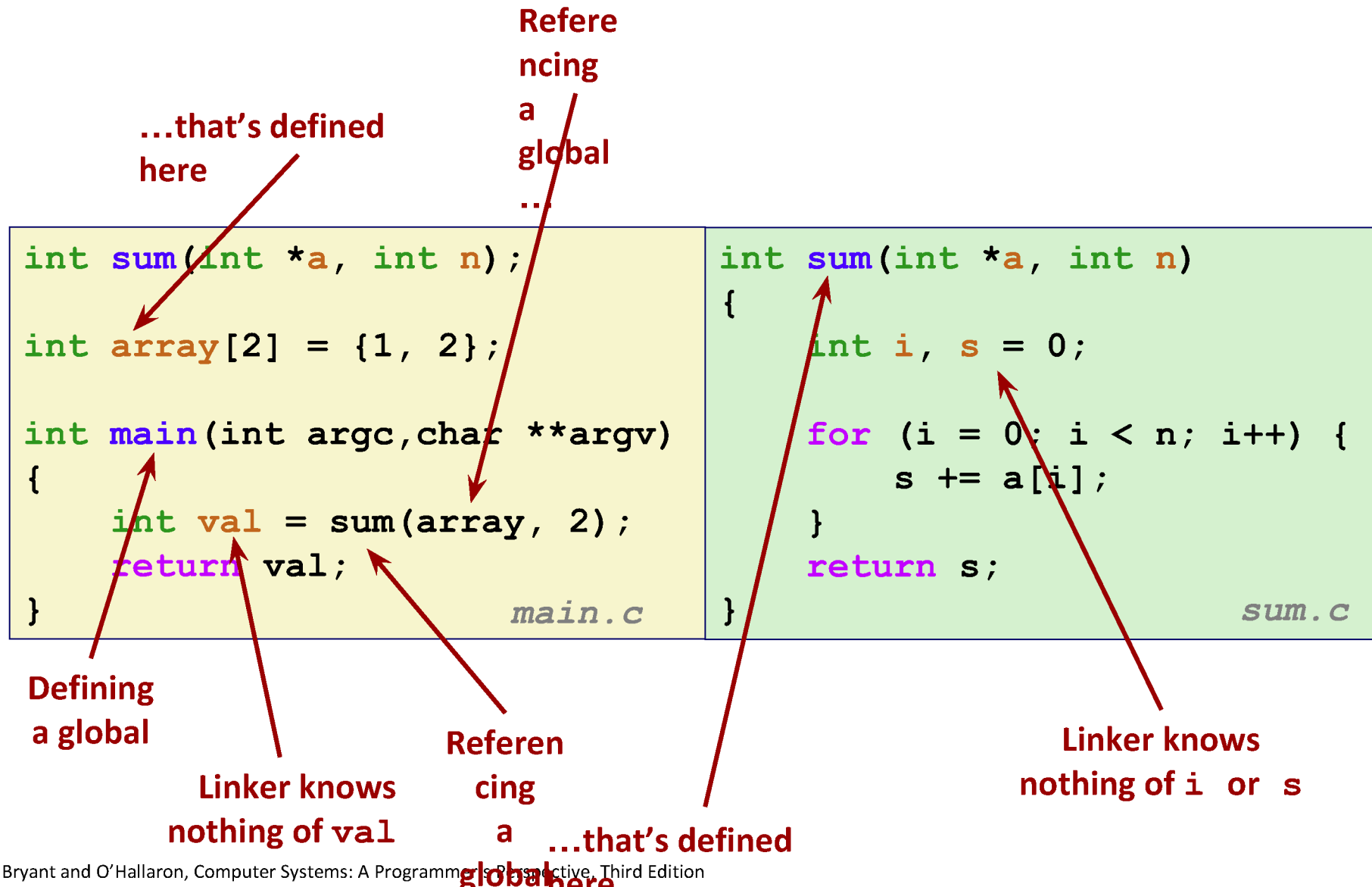
## ■ External symbols

- Global symbols that are referenced by module  $m$  but defined by some other module.

## ■ Local symbols

- Symbols that are defined and referenced exclusively by module  $m$ .
- E.g.: C functions and global variables defined with the `static` attribute.
- **Local linker symbols are *not* local program variables**

# Step 1: Symbol Resolution



# Symbol Identification

*How many of the following names will be in the symbol table of main.o?*

main.c:

```
int time;

int foo(int a) {
    int b = a + 1;
    return b;
}

int main(int
argc,
           char**
argv) {
    printf("%d",
foo(5));
return 0;
}
```

Names:

- time
- foo
- a
- b
- main
- argc
- argv
- prin

From Sat Garcia, U. San Diego, used with permission

# Symbol Identification

*How many of the following names will be in the symbol table of main.o?*

main.c:

```
int time;

int foo(int a) {
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    return b;
}

int main(int
argc,
        char**
argv) {
    printf("%d",
foo(5));
return 0;
}
```

Names:

- time
- foo
- a
- b
- main
- argc
- argv
- prin
- t f



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# Local Symbols

## ■ Local non-static C variables vs. local static C variables

- local non-static C variables: stored on the stack
- local static C variables: stored in either `.bss`, or `.data`

```
static int x = 15;

int f() {
    static int x = 17;
    return x++;
}

int g() {
    static int x = 19;
    return x += 14;
}

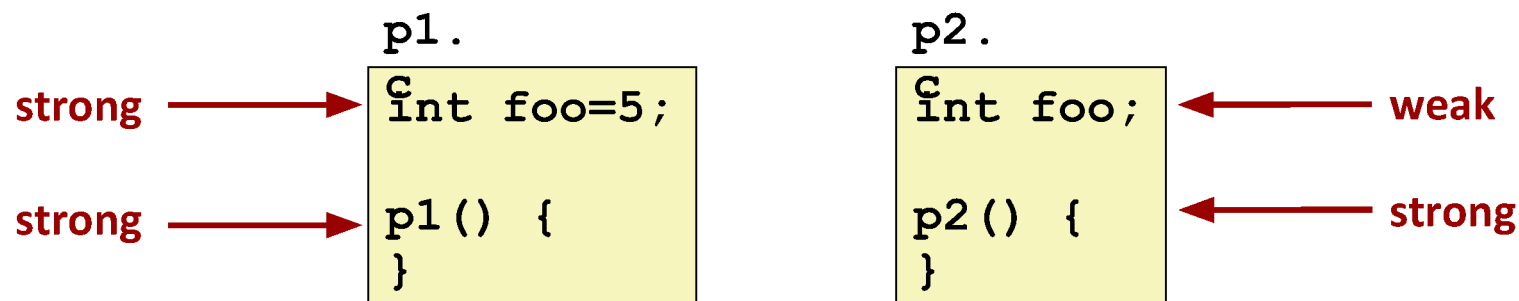
int h() {
    return x += 27;
}
static-local.c
```

Compiler allocates space in `.data` for each definition of `x`

Creates local symbols in the symbol table with unique names, e.g., `x`, `x.1721` and `x.1724`.

# How Linker Resolves Duplicate Symbol Definitions

- Program symbols are either *strong* or *weak*
  - **Strong**: procedures and initialized globals
  - **Weak**: uninitialized globals



# Linker's Symbol Rules

- **Rule 1: Multiple strong symbols are not allowed**
  - Each item can be defined only once
  - Otherwise: Linker error
  
- **Rule 2: Given a strong symbol and multiple weak symbols, choose the strong symbol**
  - References to the weak symbol resolve to the strong symbol
  
- **Rule 3: If there are multiple weak symbols, pick an arbitrary one**
  - Can override this with `gcc -fno-common`
  
- **Puzzles on the next slide**

# Linker Puzzles

```
int x;
p1() {}
```

```
p1() {}
```

Link time error: two strong symbols (**p1**)

```
int x;
p1() {}
```

```
int x;
p2() {}
```

References to **x** will refer to the same uninitialized int. Is this what you really want?

```
int x;
int y;
p1() {}
```

```
double x;
p2() {}
```

Writes to **x** in **p2** might overwrite **y**!  
Evil!

```
int x=7;
int y=5;
p1() {}
```

```
double x;
p2() {}
```

Writes to **x** in **p2** will overwrite **y**!  
Nasty!

```
int x=7;
p1() {}
```

```
int x;
p2() {}
```

References to **x** will refer to the same initialized variable.

**Nightmare scenario: two identical weak structs, compiled by different compilers with different alignment rules.**

# Global Variables

- **Avoid if you can**
  
- **Otherwise**
  - Use `static` if you can
  - Initialize if you define a global variable
  - Use `extern` if you reference an external global variable

# Role of .h Files

c1.c

```
#include "global.h"

int f() {
    return g+1;
}
```

global.h

```
extern int g;
static int init = 0;
```

```
#else
    extern int g;
    static int init = 0;
#endif
```

c2.c

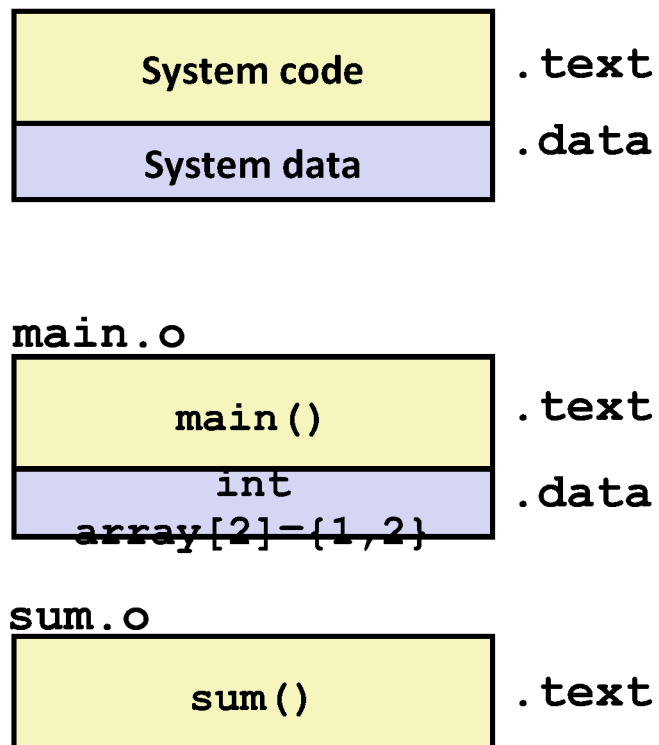
```
#define INITIALIZE
#include <stdio.h>
#include "global.h"

int main(int argc, char** argv) {
    if (init)
        // do something, e.g., g=31;
    int t = f();
    printf("Calling f yields %d\n", t);
    return 0;
}
```

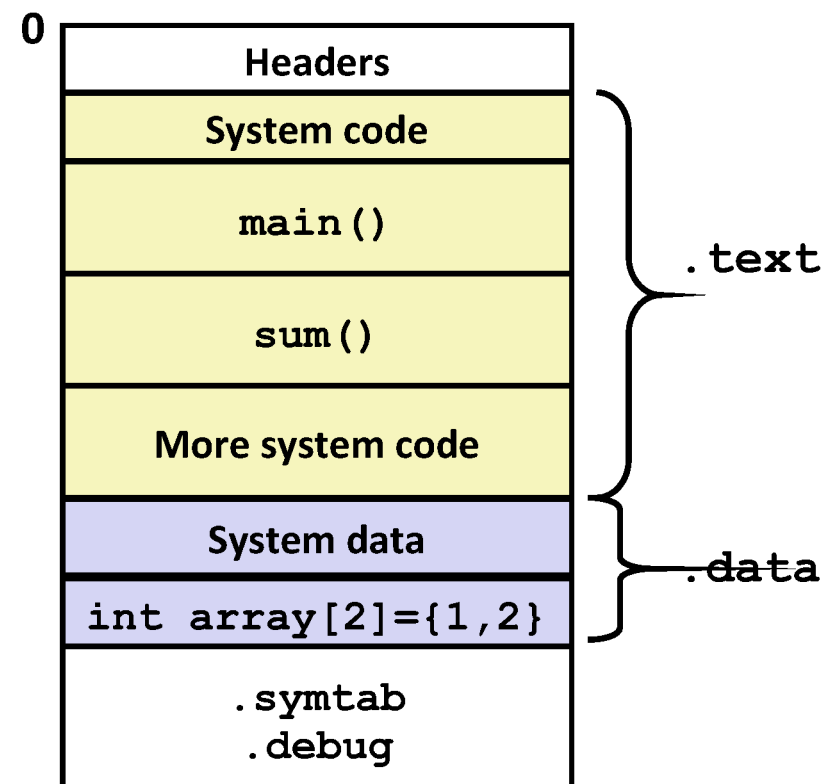
```
int g = 23;
static int init = 1;
```

# Step 2: Relocation

## Relocatable Object Files



## Executable Object File



# Relocation Entries

```
int array[2] = {1, 2};

int main(int argc, char**
argv)
{
    int val = sum(array, 2);
    return val;
}                                     main.c
```

```
0000000000000000 <main>:
 0:  48 83 ec 08          sub    $0x8,%rsp
 4:  be 02 00 00 00      mov    $0x2,%esi
 9:  bf 00 00 00 00      mov    $0x0,%edi          # %edi = &array
                          a: R_X86_64_32 array      # Relocation entry

 e:  e8 00 00 00 00      callq 13 <main+0x13>     # sum()
                          f: R_X86_64_PC32 sum-0x4  # Relocation entry
13:  48 83 c4 08          add    $0x8,%rsp
17:  c3                  retq

                                                                    main.o
```



# Relocated .text section

```

00000000004004d0 <main>:
 4004d0:      48 83 ec 08      sub    $0x8,%rsp
 4004d4:      be 02 00 00 00   mov    $0x2,%esi
 4004d9:      bf 18 10 60 00   mov    $0x601018,%edi # %edi = &array
 4004de:      e8 05 00 00 00   callq 4004e8 <sum>    # sum()
4004e3:      48 83 c4 08      add    $0x8,%rsp
 4004e7:      c3              retq

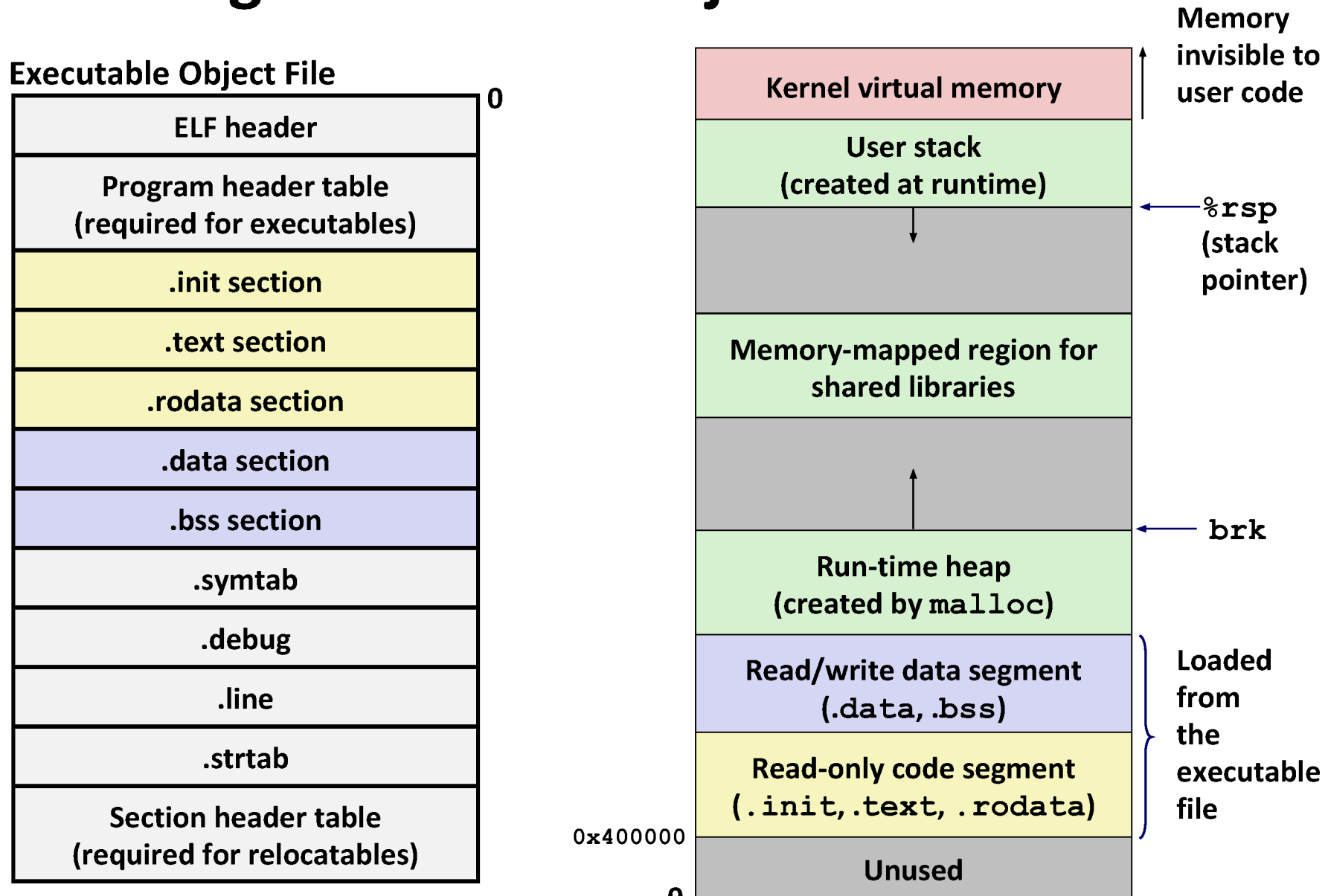
00000000004004e8 <sum>:
4004e8:      b8 00 00 00 00   mov    $0x0,%eax
 4004ed:      ba 00 00 00 00   mov    $0x0,%edx
 4004f2:      eb 09           jmp    4004fd <sum+0x15>
 4004f4:      48 63 ca       movslq %edx,%rcx
 4004f7:      03 04 8f       add    (%rdi,%rcx,4),%eax
 4004fa:      83 c2 01       add    $0x1,%edx
 4004fd:      39 f2         cmp    %esi,%edx
 4004ff:      7c f3         jl    4004f4 <sum+0xc>
 400501:      f3 c3       repz retq

```

`callq` instruction uses PC-relative addressing for `sum()`:

$$0x4004e8 = 0x4004e3 + 0x5$$

# Loading Executable Object Files



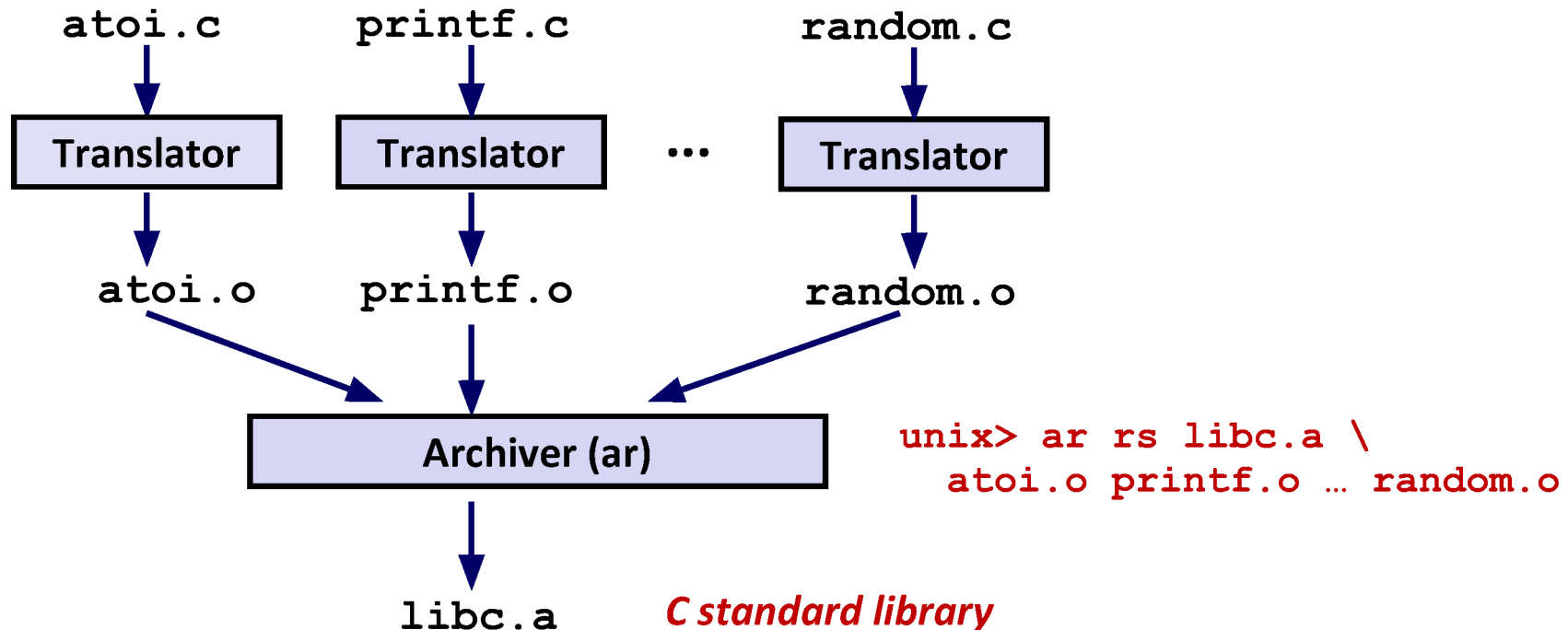
# Packaging Commonly Used Functions

- **How to package functions commonly used by programmers?**
  - Math, I/O, memory management, string manipulation, etc.
  
- **Awkward, given the linker framework so far:**
  - **Option 1:** Put all functions into a single source file
    - Programmers link big object file into their programs
    - Space and time inefficient
  - **Option 2:** Put each function in a separate source file
    - Programmers explicitly link appropriate binaries into their programs
    - More efficient, but burdensome on the programmer

# Old-fashioned Solution: Static Libraries

- **Static libraries** (.a archive files)
  - Concatenate related relocatable object files into a single file with an index (called an *archive*).
  - Enhance linker so that it tries to resolve unresolved external references by looking for the symbols in one or more archives.
  - If an archive member file resolves reference, link it into the executable.

# Creating Static Libraries



- Archiver allows incremental updates
- Recompile function that changes and replace .o file in archive.

# Commonly Used Libraries

## `libc.a` (the C standard library)

- 4.6 MB archive of 1496 object files.
- I/O, memory allocation, signal handling, string handling, data and time, random numbers, integer math

## `libm.a` (the C math library)

- 2 MB archive of 444 object files.
- floating point math (sin, cos, tan, log, exp, sqrt, ...)

```
% ar -t libc.a | sort
...
fork.o
...
fprintf.o
fpu_control.o
fputc.o
freopen.o
fscanf.o
fseek.o
fstab.o
...
```

```
% ar -t libm.a | sort
...
e_acos.o
e_acosf.o
e_acosh.o
e_acoshf.o
e_acoshl.o
e_acosl.o
e_asin.o
e_asinf.o
e_asinl.o
...
```

# Linking with Static Libraries

```
#include <stdio.h>
#include "vector.h"

int x[2] = {1, 2};
int y[2] = {3, 4};
int z[2];

int main(int argc, char**
argv)
{
    addvec(x, y, z, 2);
    printf("z = [%d %d]\n",
        z[0], z[1]);
    return 0;          main2.c
}
```

libvector.a



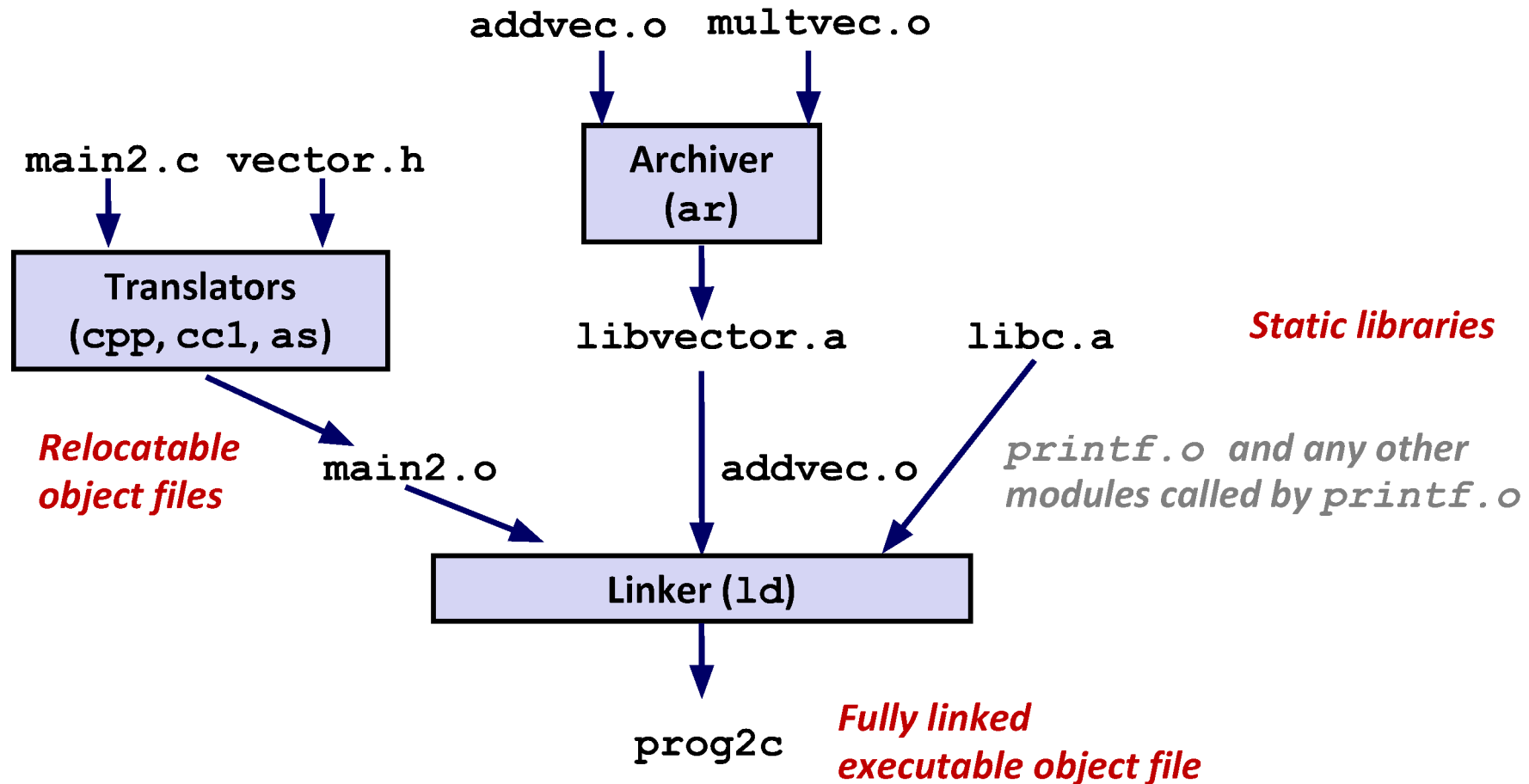
```
void addvec(int *x, int *y,
            int *z, int n) {
    int i;

    for (i = 0; i < n; i++)
        z[i] = x[i] + y[i];
}          addvec.c
```

```
void multvec(int *x, int *y,
             int *z, int n)
{
    int i;

    for (i = 0; i < n; i++)
        z[i] = x[i] * y[i];
}          multvec.c
```

# Linking with Static Libraries



*“c” for “compile-time”*



# Using Static Libraries

- **Linker's algorithm for resolving external references:**
  - Scan `.o` files and `.a` files in the command line order.
  - During the scan, keep a list of the current unresolved references.
  - As each new `.o` or `.a` file, *obj*, is encountered, try to resolve each unresolved reference in the list against the symbols defined in *obj*.
  - If any entries in the unresolved list at end of scan, then error.
- **Problem:**
  - Command line order matters!
  - Moral: put libraries at the end of the command line.

```
unix> gcc -L. libtest.o -lmine
unix> gcc -L. -lmine libtest.o
libtest.o: In function 'main':
libtest.o(.text+0x4): undefined reference to 'libfun'
```

# Modern Solution: Shared Libraries

- **Static libraries have the following disadvantages:**
  - Duplication in the stored executables (every function needs libc)
  - Duplication in the running executables
  - Minor bug fixes of system libraries require each application to explicitly relink
    - Rebuild everything with glibc?
    - <https://security.googleblog.com/2016/02/cve-2015-7547-glibc-getaddrinfo-stack.html>
  
- **Modern solution: Shared Libraries**
  - Object files that contain code and data that are loaded and linked into an application *dynamically*, at either *load-time* or *run-time*
  - Also called: dynamic link libraries, DLLs, `.so` files

# Shared Libraries (cont.)

- **Dynamic linking can occur when executable is first loaded and run (load-time linking).**
  - Common case for Linux, handled automatically by the dynamic linker (`ld-linux.so`).
  - Standard C library (`libc.so`) usually dynamically linked.
- **Dynamic linking can also occur after program has begun (run-time linking).**
  - In Linux, this is done by calls to the `dlopen()` interface.
    - Distributing software.
    - High-performance web servers.
    - Runtime library interpositioning.
- **Shared library routines can be shared by multiple processes.**
  - More on this when we learn about virtual memory

# What dynamic libraries are required?

## ■ .interp section

- Specifies the dynamic linker to use (i.e., `ld-linux.so`)

## ■ .dynamic section

- Specifies the names, etc of the dynamic libraries to use
- Follow an example of `csim-ref` from `cachelab`

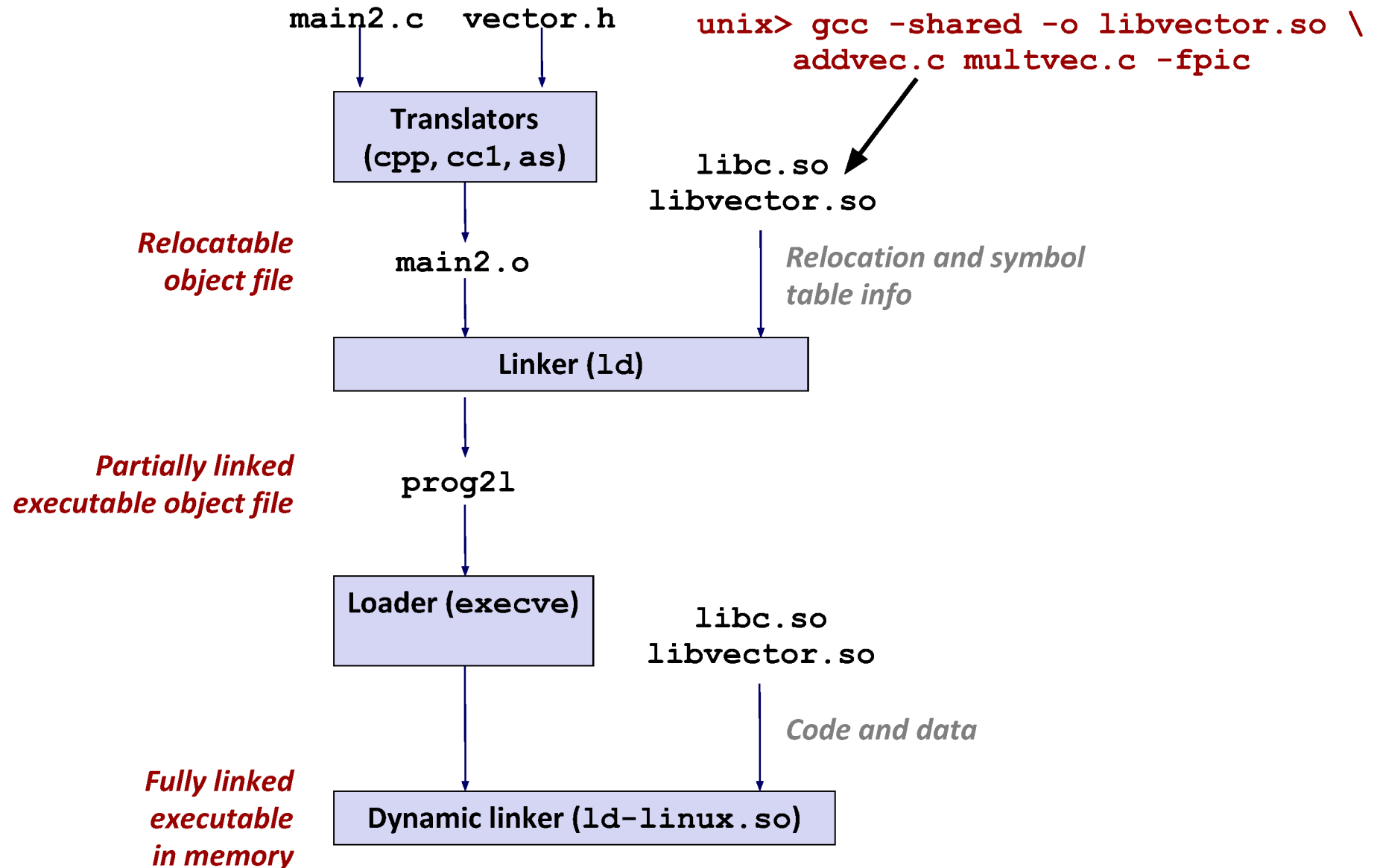
```
(NEEDED)                Shared library: [libm.so.6]
```

## ■ Where are the libraries found?

- Use “`ldd`” to find out:

```
unix> ldd csim-ref
linux-vdso.so.1 => (0x00007ffc195f5000)
libc.so.6 => /lib/x86_64-linux-gnu/libc.so.6 (0x00007f345eda6000)
/lib64/ld-linux-x86-64.so.2 (0x00007f345f181000)
```

# Dynamic Linking at Load-time



# Dynamic Linking at Run-time

```
#include <stdio.h>
#include <stdlib.h>
#include <dlfcn.h>

int x[2] = {1, 2};
int y[2] = {3, 4};
int z[2];

int main(int argc, char** argv)
{
    void *handle;
    void (*addvec)(int *, int *, int *, int);
    char *error;

    /* Dynamically load the shared library that contains addvec() */
    handle = dlopen("./libvector.so", RTLD_LAZY);
    if (!handle) {
        fprintf(stderr, "%s\n", dlerror());
        exit(1);
    }
    . . .
}
```

*dll.c*

# Dynamic Linking at Run-time (cont)

```
...

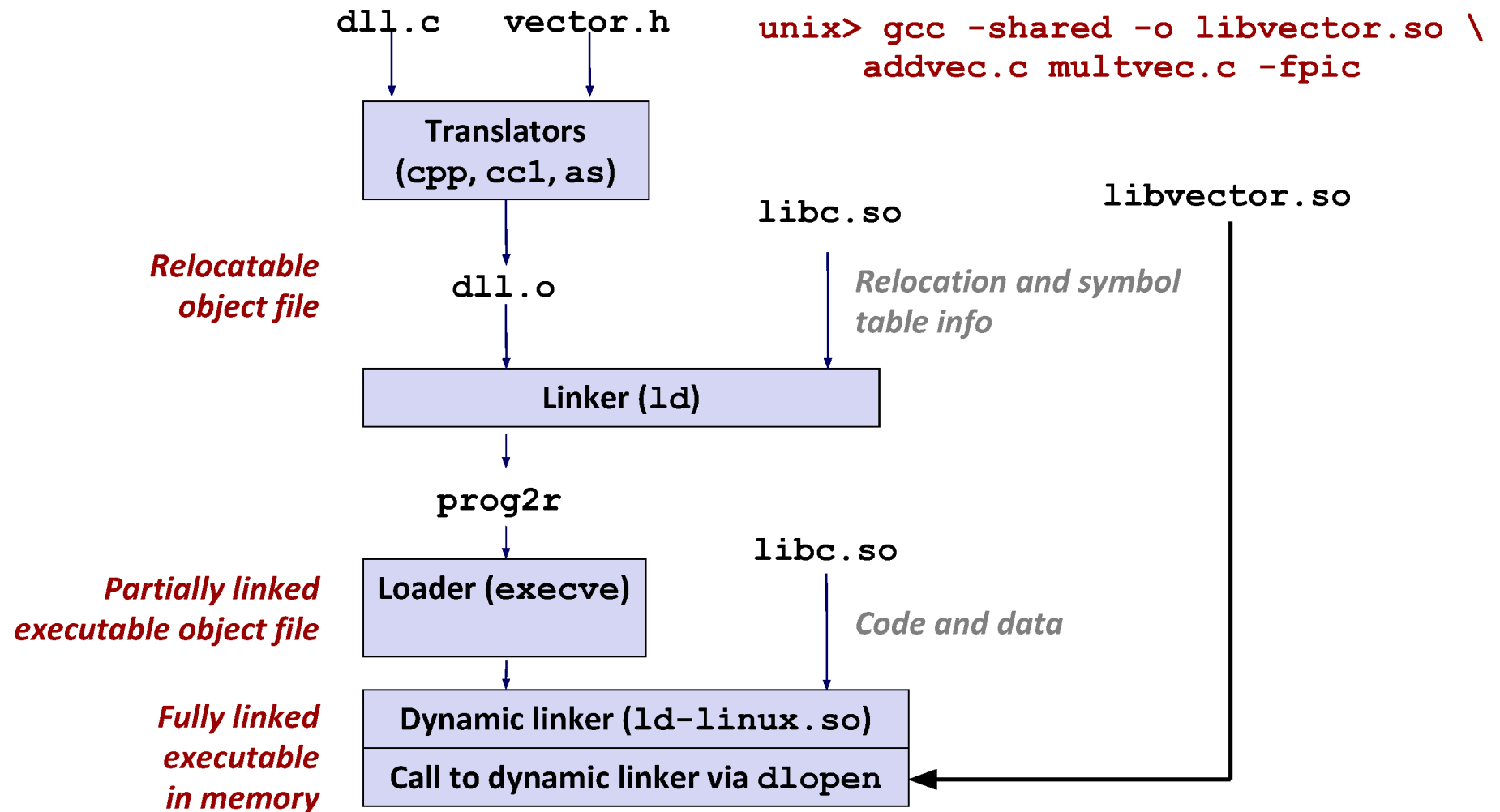
/* Get a pointer to the addvec() function we just loaded */
addvec = dlsym(handle, "addvec");
if ((error = dlerror()) != NULL) {
    fprintf(stderr, "%s\n", error);
    exit(1);
}

/* Now we can call addvec() just like any other function */
addvec(x, y, z, 2);
printf("z = [%d %d]\n", z[0], z[1]);

/* Unload the shared library */
if (dlclose(handle) < 0) {
    fprintf(stderr, "%s\n", dlerror());
    exit(1);
}
return 0;
}

d11.c
```

# Dynamic Linking at Run-time





# Linking Summary

- **Linking is a technique that allows programs to be constructed from multiple object files.**
  
- **Linking can happen at different times in a program's lifetime:**
  - Compile time (when a program is compiled)
  - Load time (when a program is loaded into memory)
  - Run time (while a program is executing)
  
- **Understanding linking can help you avoid nasty errors and make you a better programmer.**