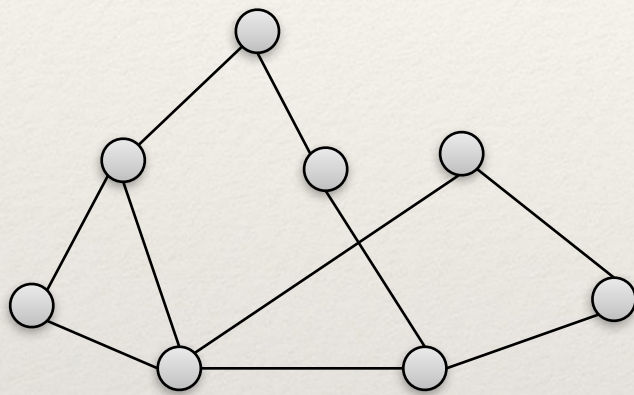

Approximating Graphs by Trees

Marcin Bieńkowski

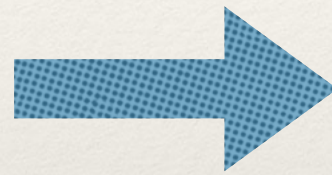
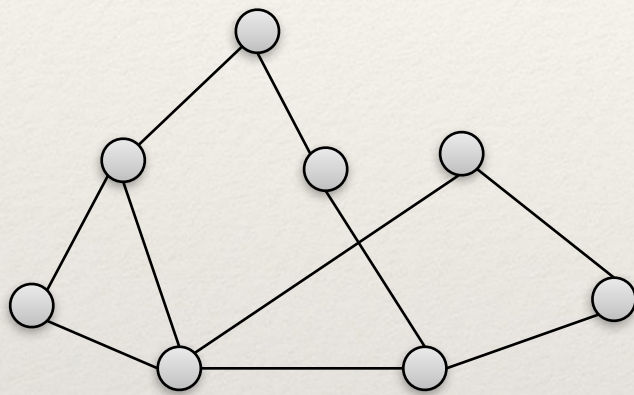
The problem

Given an arbitrary graph
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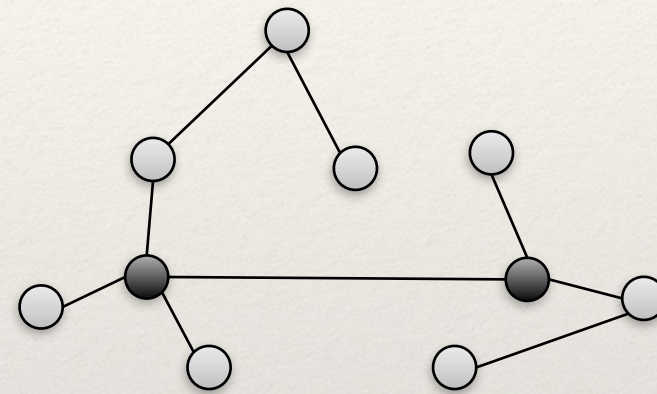


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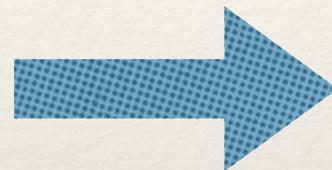
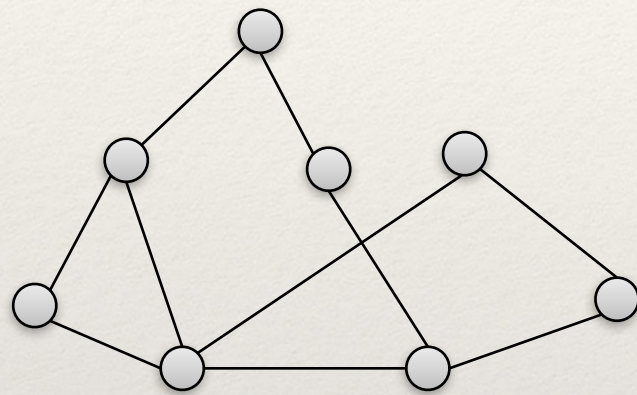


... construct a tree $T = (V', E')$
with $V \subseteq V' \dots$

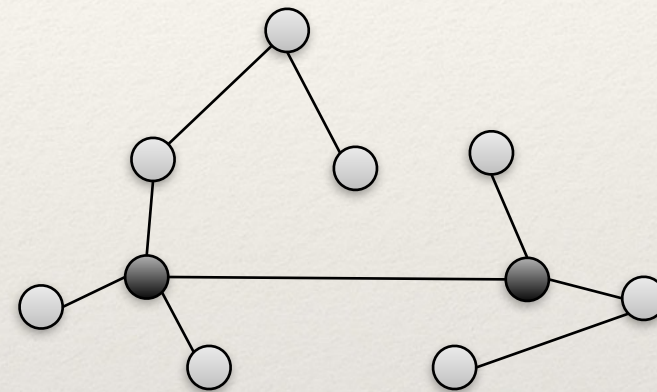


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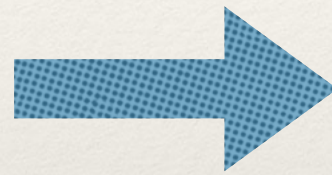
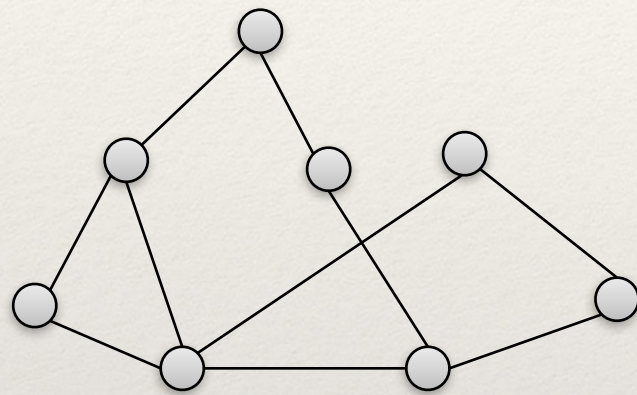
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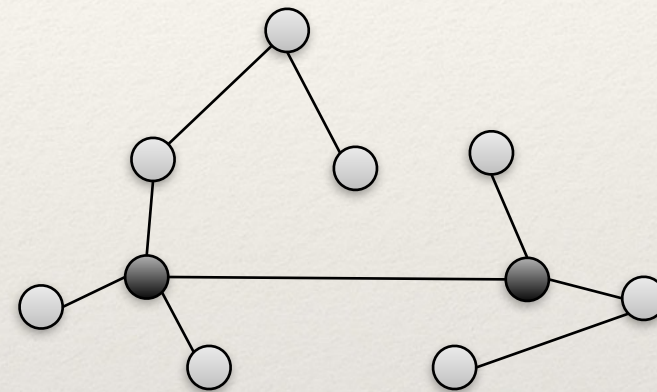
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any pair u, v of vertices: $d_{u,v} \leq T_{u,v} \leq \alpha \cdot d_{u,v}$

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distortion

Applications...

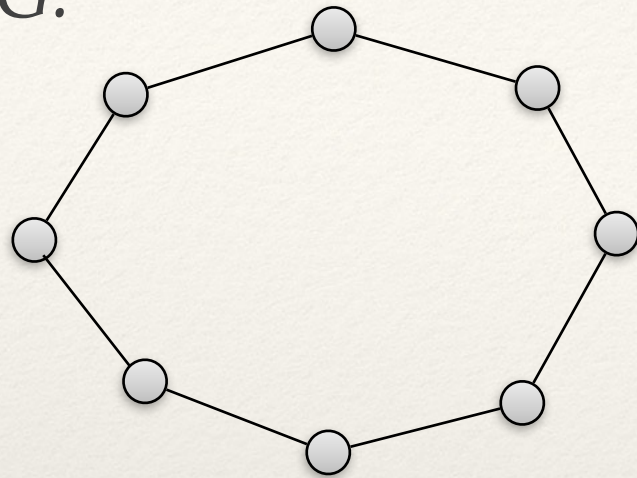
... for most of optimization problems on graphs, whose objective function is linear in distances.

In particular:

- ❖ metrical task systems
- ❖ group Steiner tree
- ❖ buy-at-bulk network design
- ❖ distributed paging
- ❖ k-server
- ❖ k-median
- ❖ ...

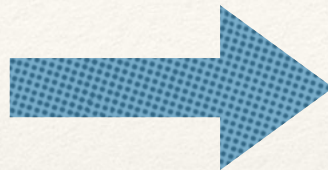
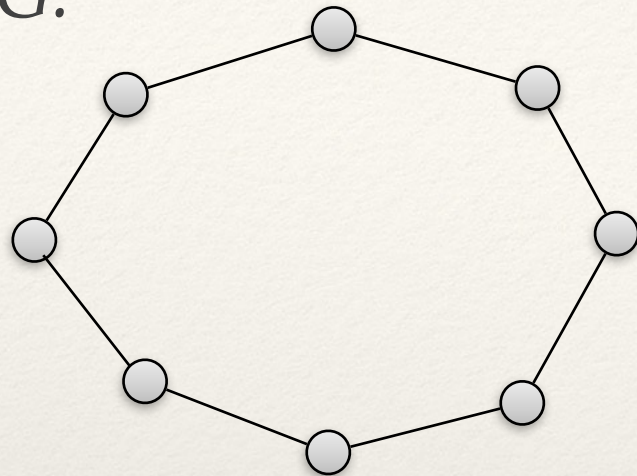
Is small distortion possible? (1)

G :

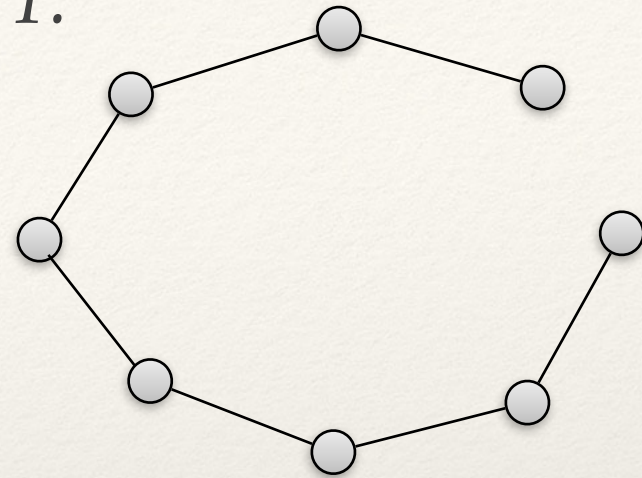


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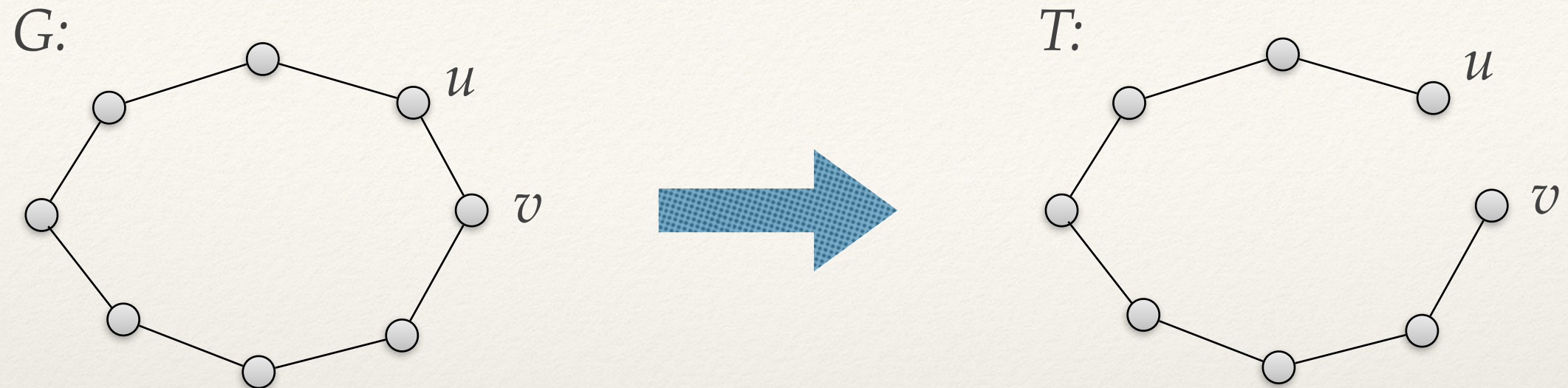
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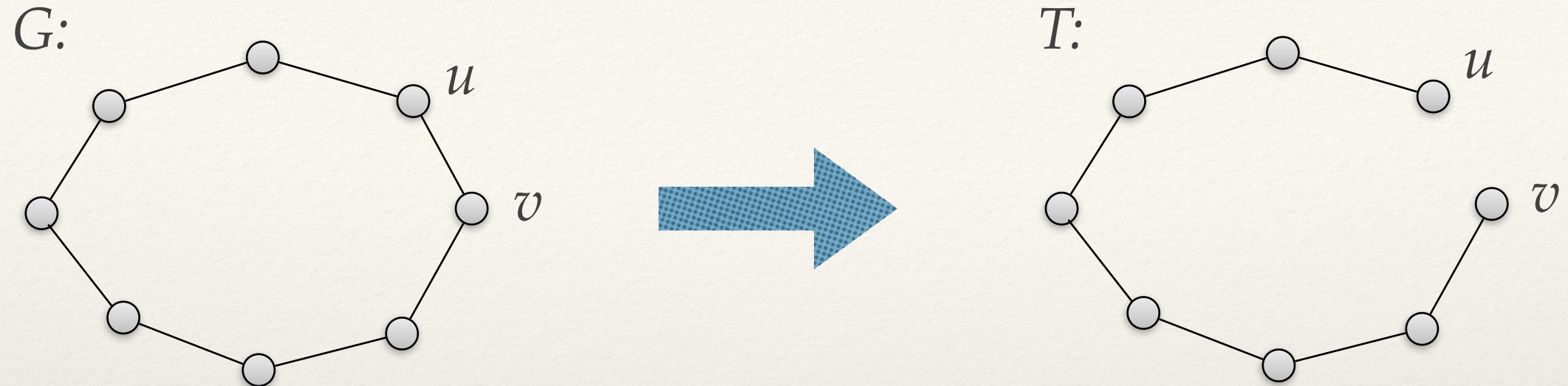
T :



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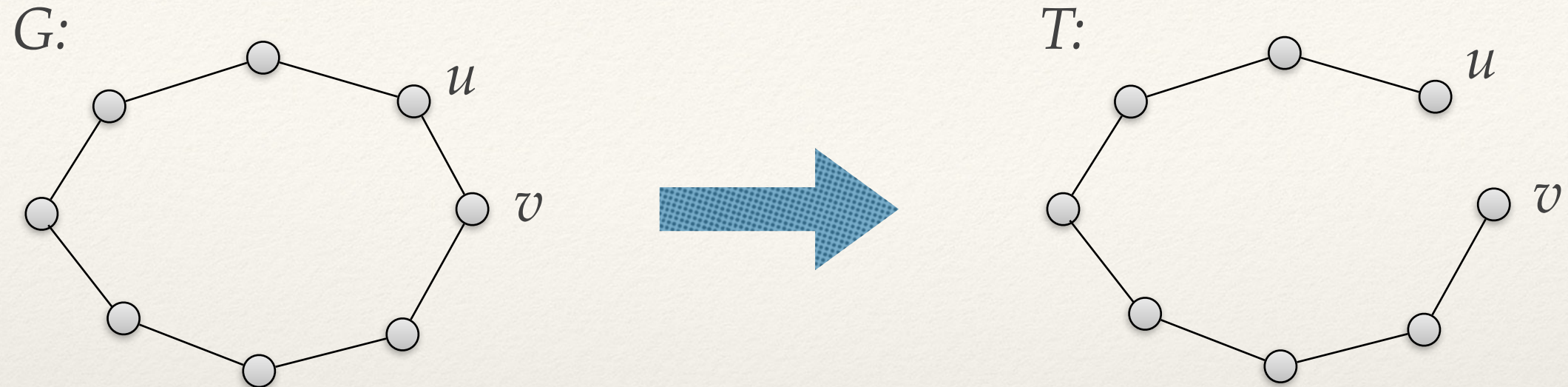


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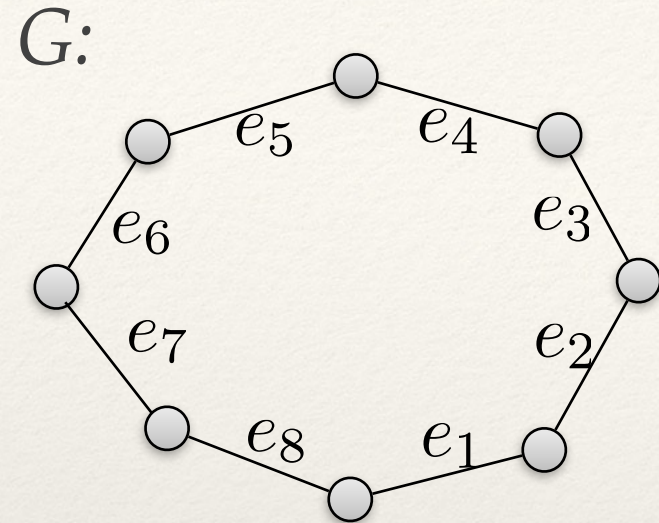
- ❖ The distortion is $n-1$.

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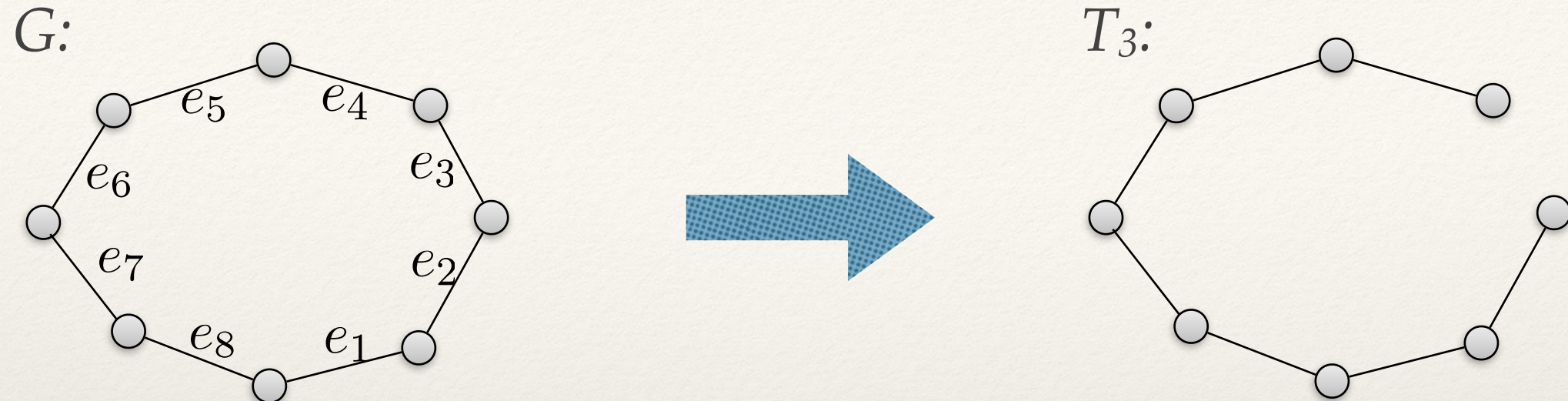


- ❖ The distortion is $n-1$.
- ❖ Actually, this is more complicated as T may contain additional nodes, but the distortion is $\Omega(n)$.
[Rabinovich, Raz 2005]
- ❖ No good **deterministic** choice of T , what about **random** one?

Is small distortion possible? (2)

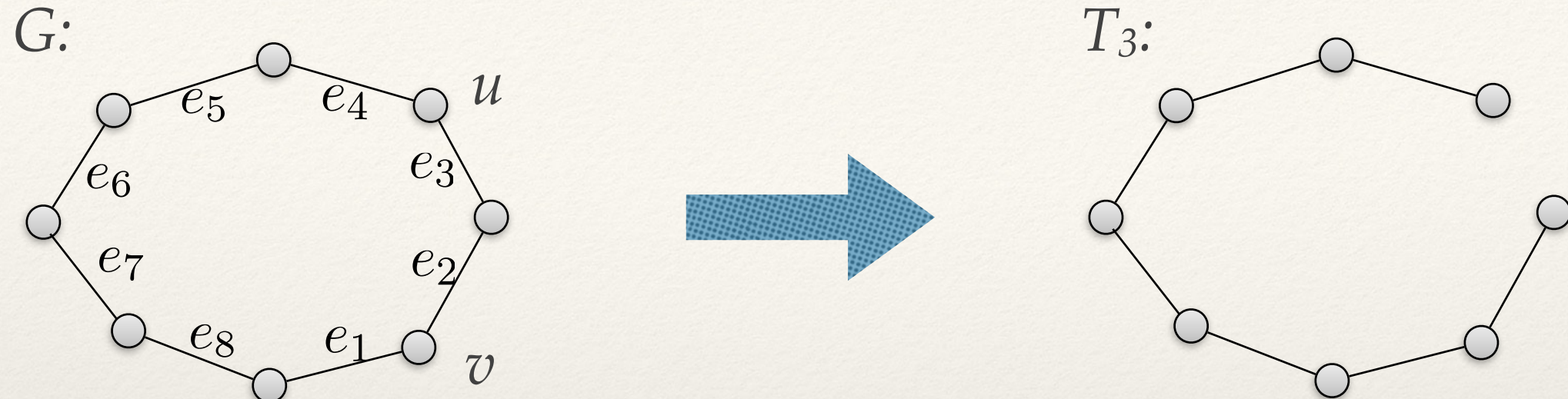


Is small distortion possible? (2)



- ❖ Cut a random edge from the circle (each with probability $1/n$) obtaining a random tree.

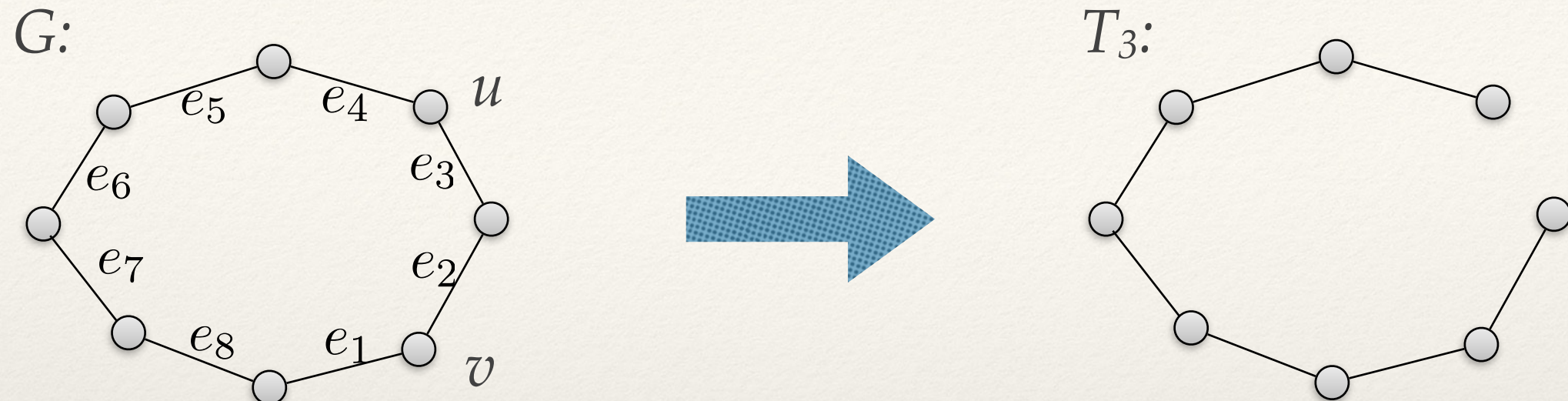
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$$\text{Then, } \mathbf{E}[T_{u,v}] = \frac{k}{n} \cdot (n - k) + \frac{n - k}{n} \cdot k = 2k \cdot \frac{n - k}{n} < 2k$$

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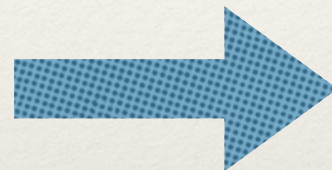
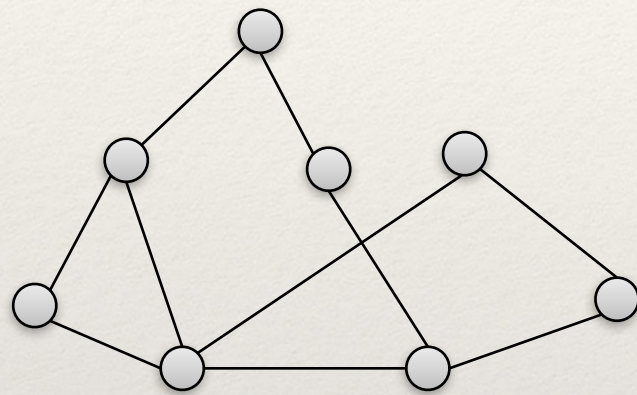
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distortion < 2

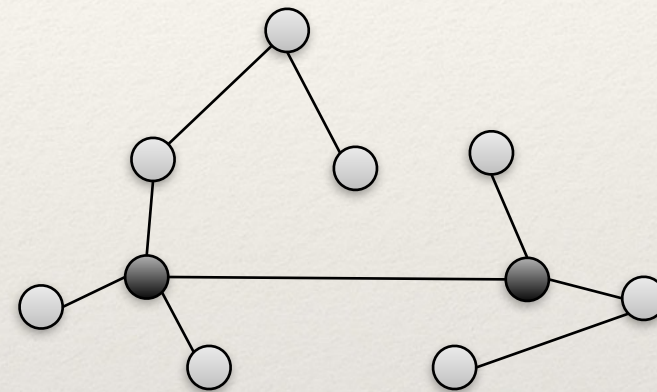
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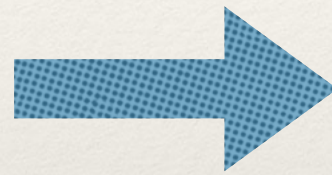
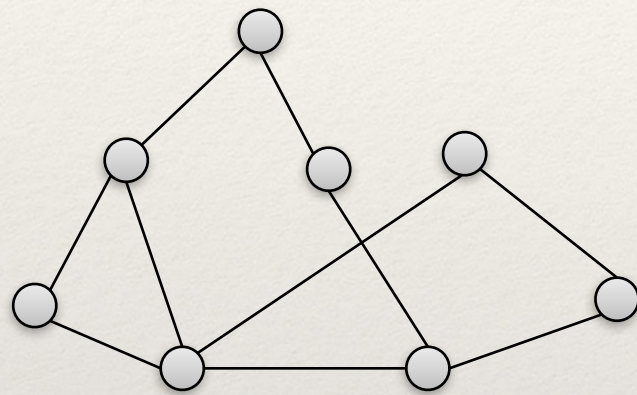


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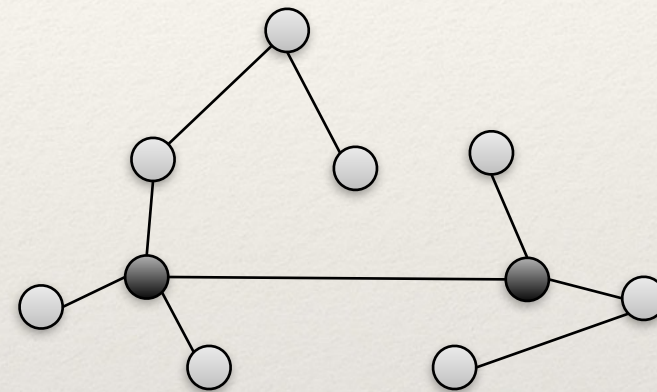


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distortion

Historical Notes

Bounding distortion:

- ❖ $2^{O(\sqrt{\log n \log \log n})}$ [Alon, Karp, Peleg, West, SIAM Jcomp '91]
- ❖ $O(\log^2 n)$ [Bartal, FOCS '96]
- ❖ $O(\log n \log \log n)$ [Bartal, STOC '98]
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The last three results use **hierarchical partitioning** of the graph.

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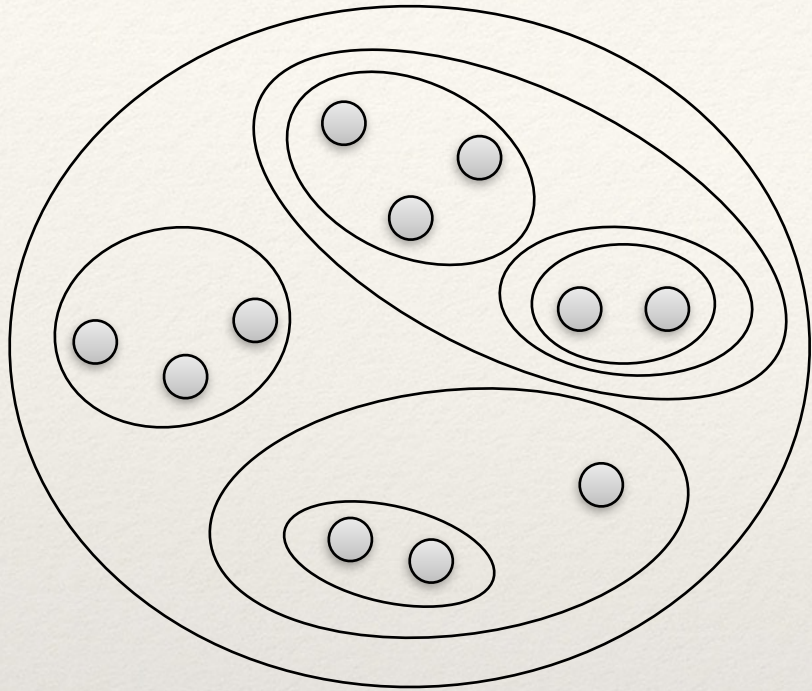
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asymptotically optimal

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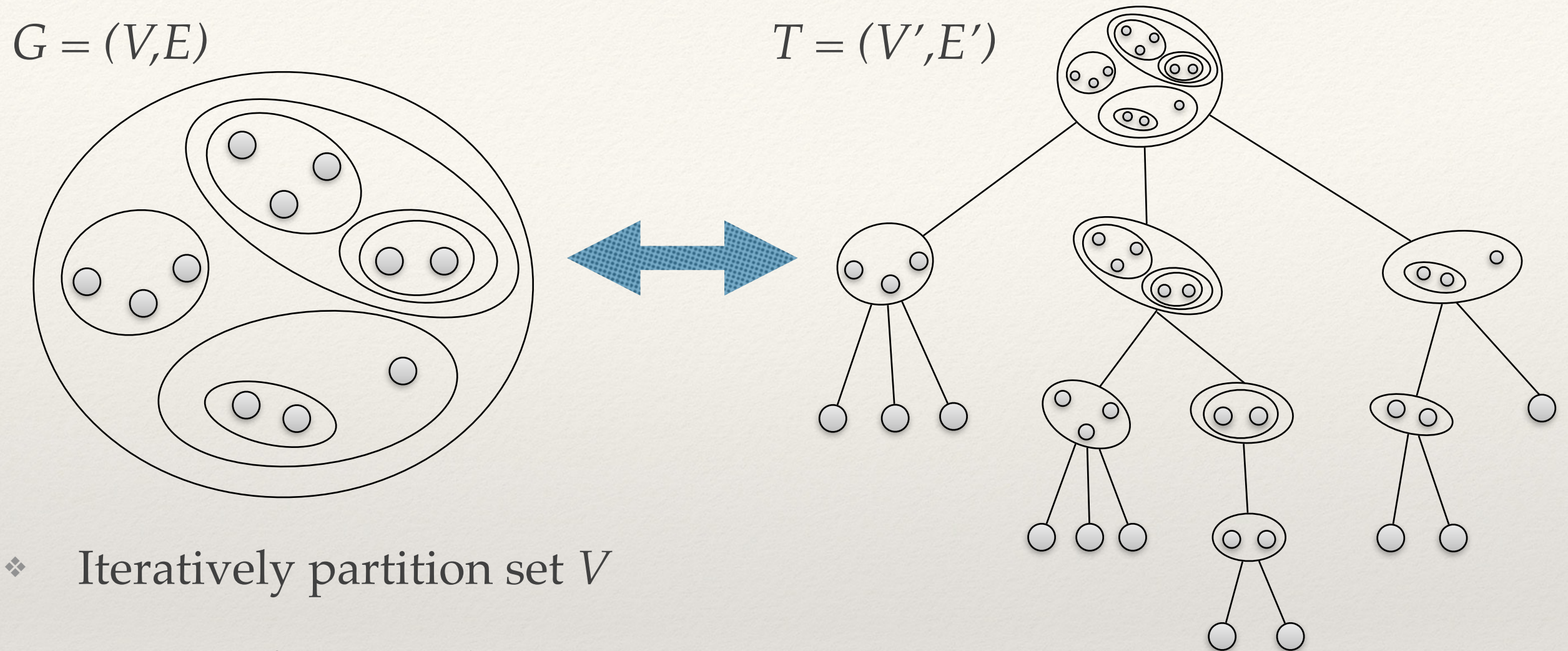
Hierarchical decomposition

$$G = (V, E)$$



- ❖ Iteratively partition set V

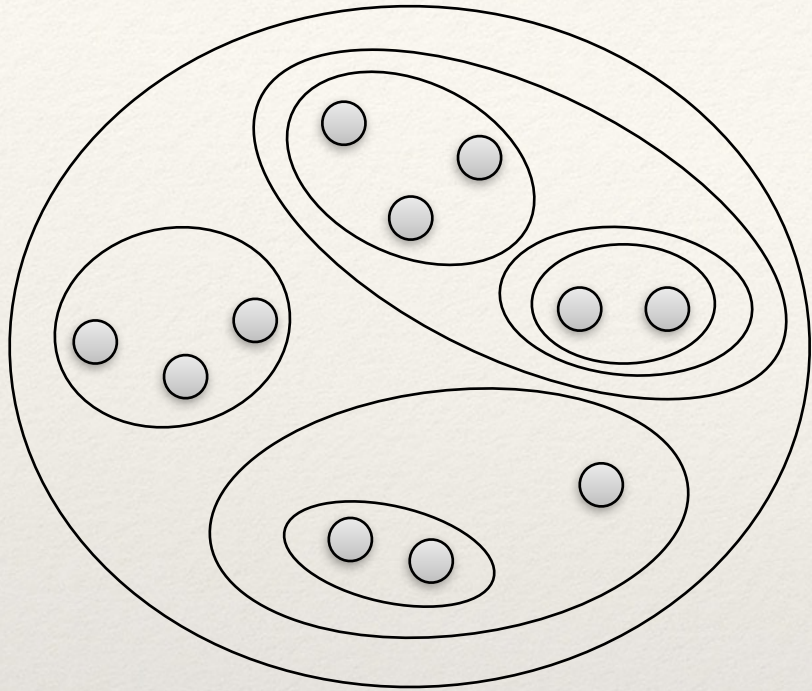
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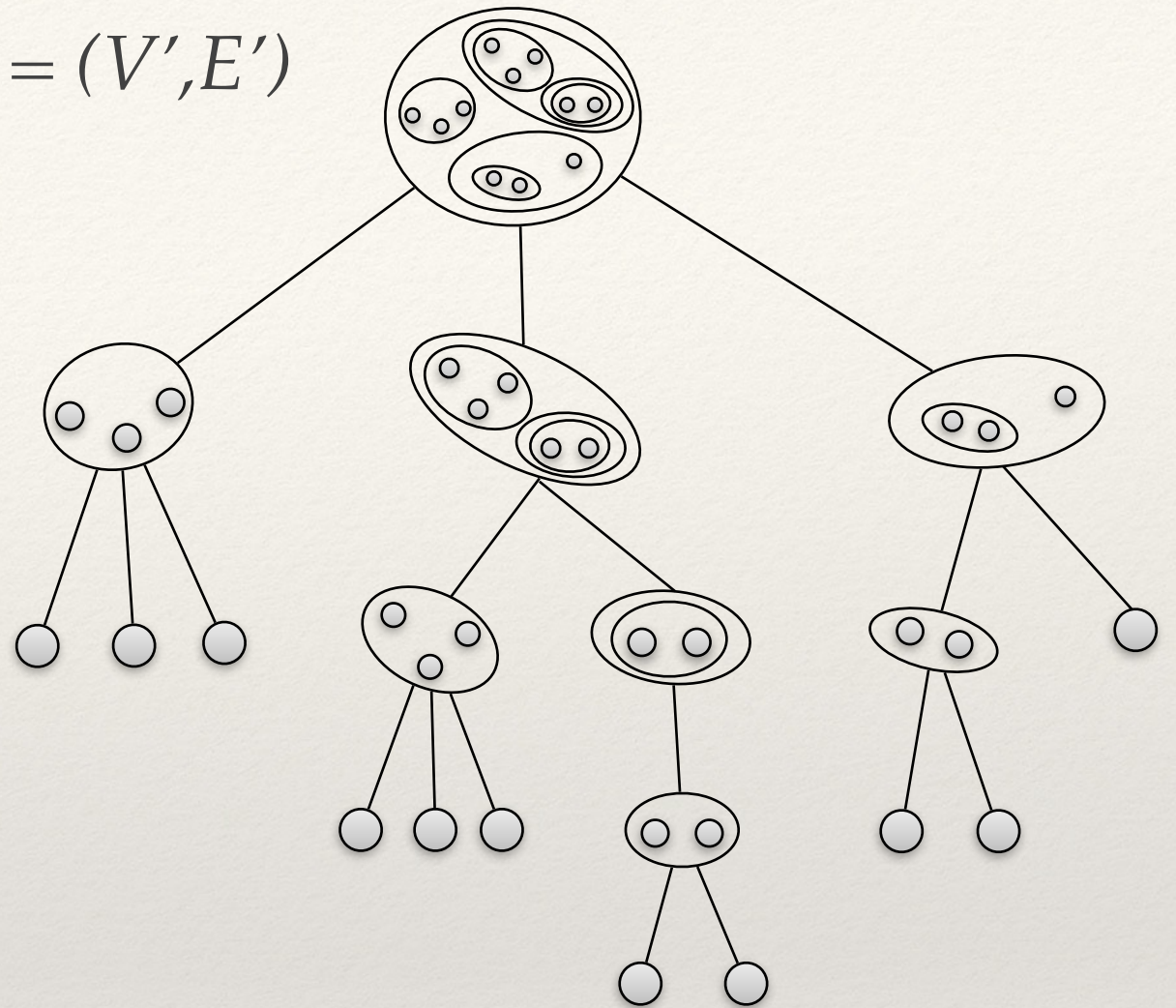
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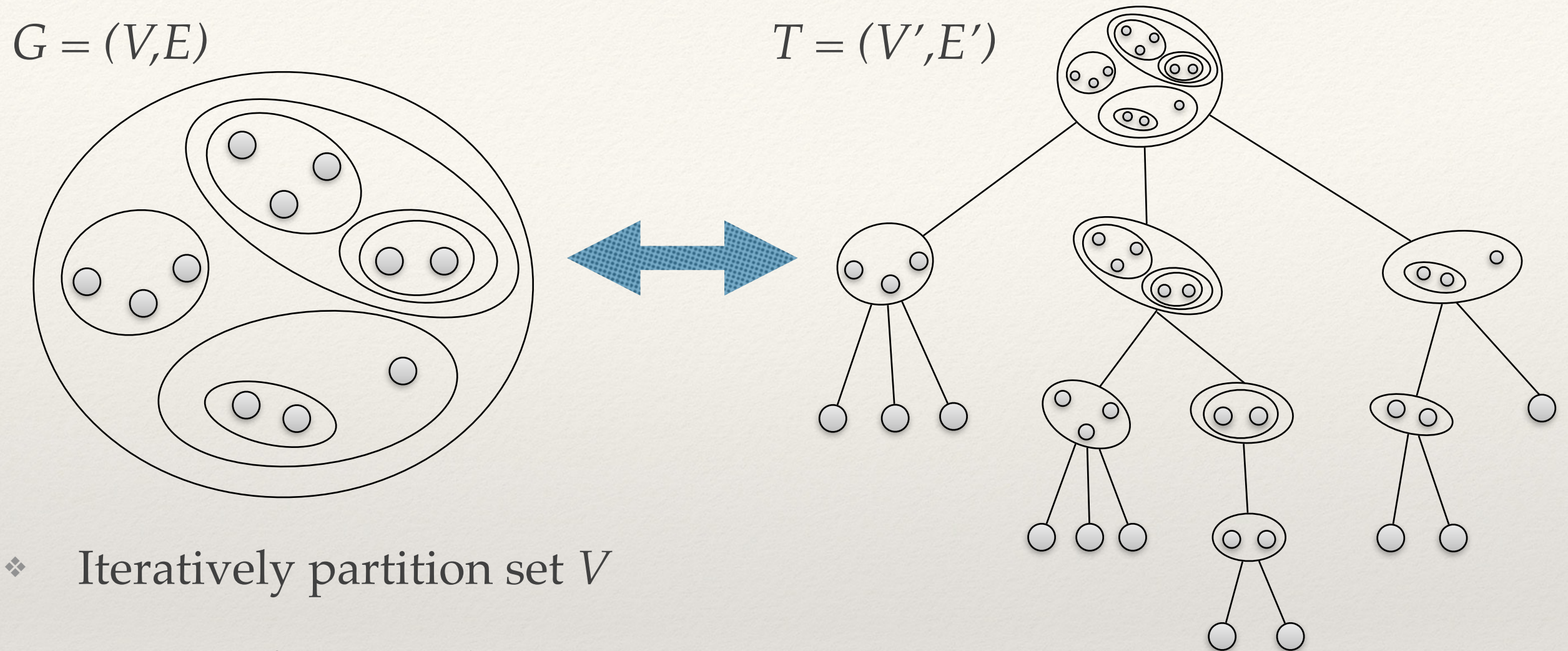


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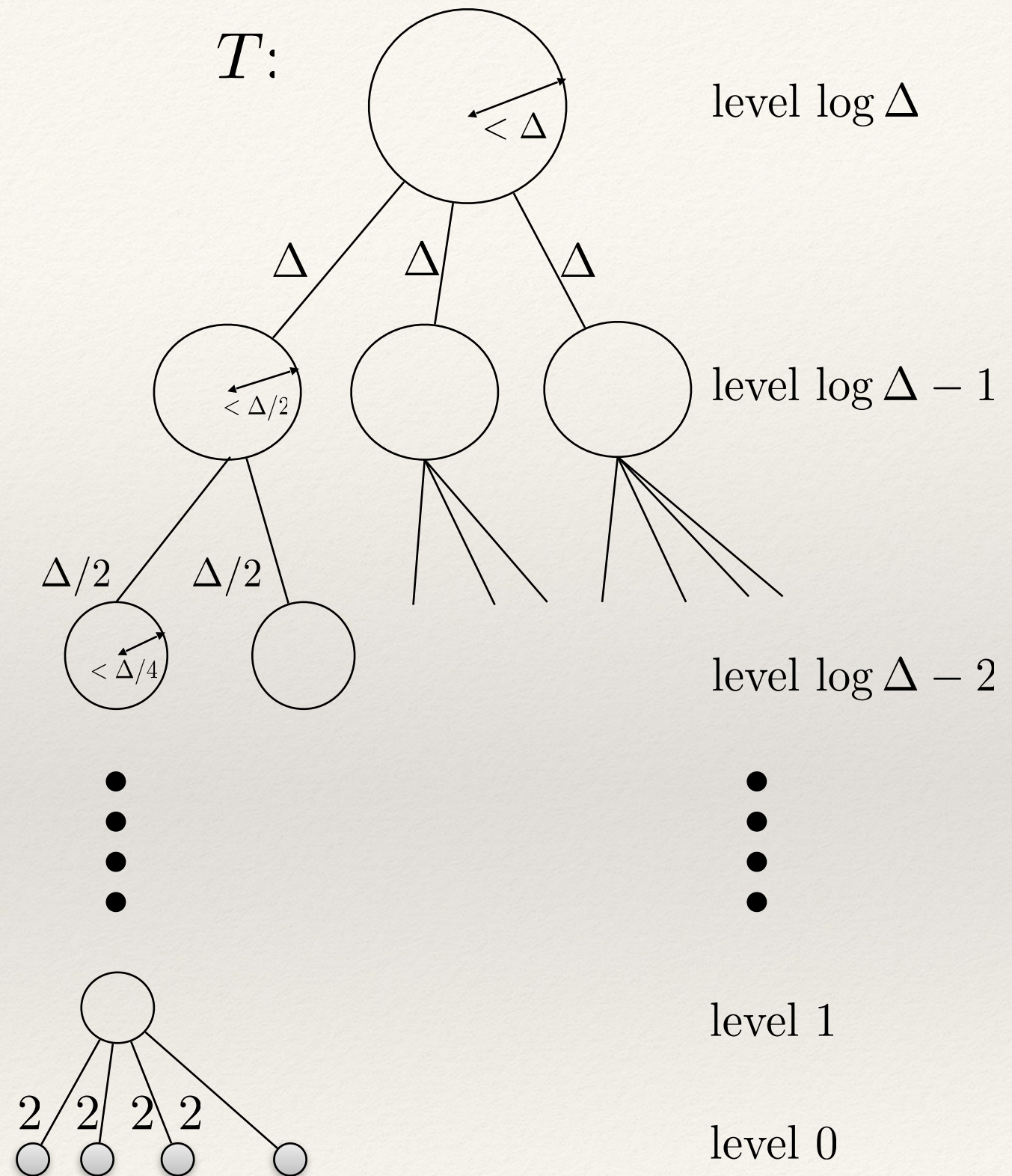
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- ❖ **How to choose partitioning of G ?**
- ❖ **How to choose distances in T ?**

Choosing tree distances

- ❖ W.l.o.g. $d_{u,v} \geq 1$
- ❖ $\Delta =$ smallest power of 2 greater than $2 \cdot \max d_{u,v}$
- ❖ FRT decomposition guarantee: for a set S on level i , there exists a ball of radius $< 2^i$ (centered at some node) containing nodes of S .

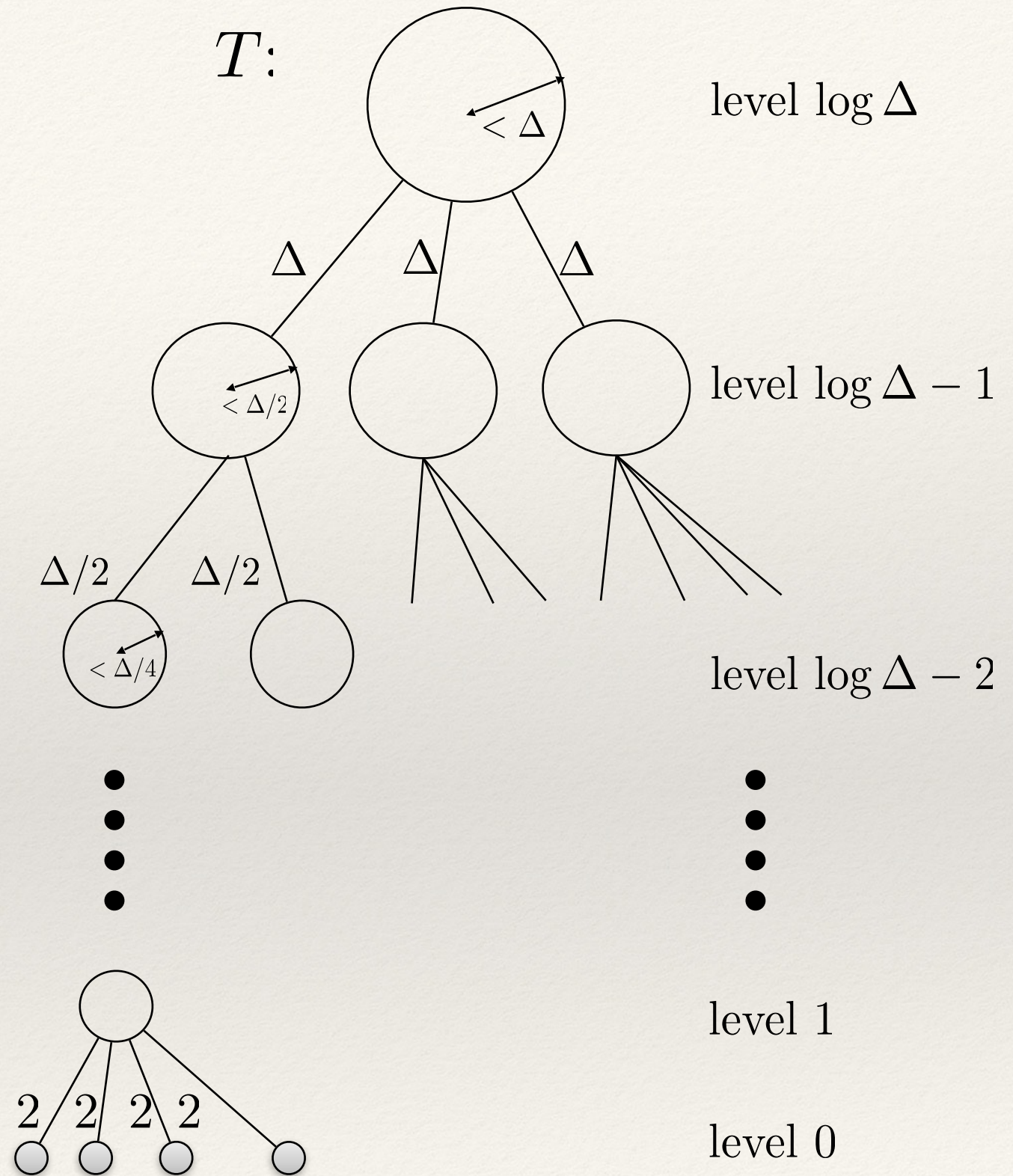


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Observation. For nodes $u, v \in V$, s.t. $\text{lca}(u, v)$ is on level i it holds that $T_{u,v} = 2^{i+2} - 4$.

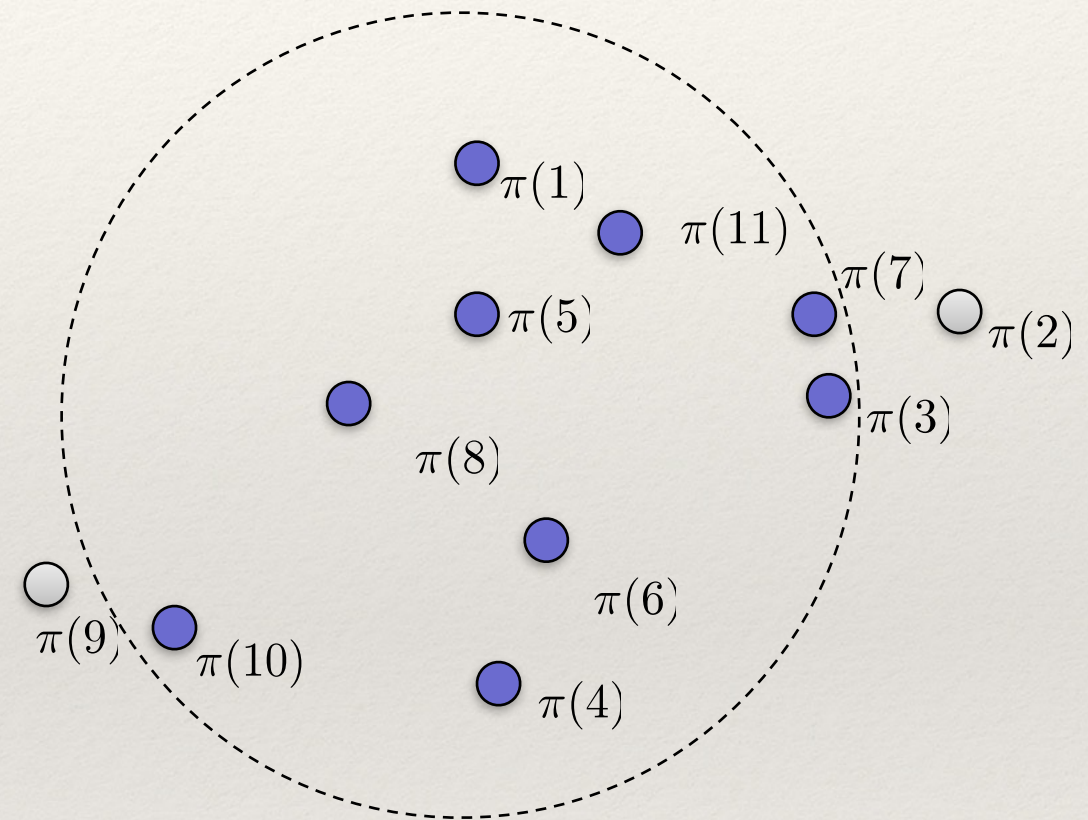
Lemma 1. $d_{u,v} \leq T_{u,v}$



Partitioning of a single set

At the beginning randomly choose $r \in [1/2, 1)$ and a random permutation π of all nodes.

Partitioning of S on level $i+1$:



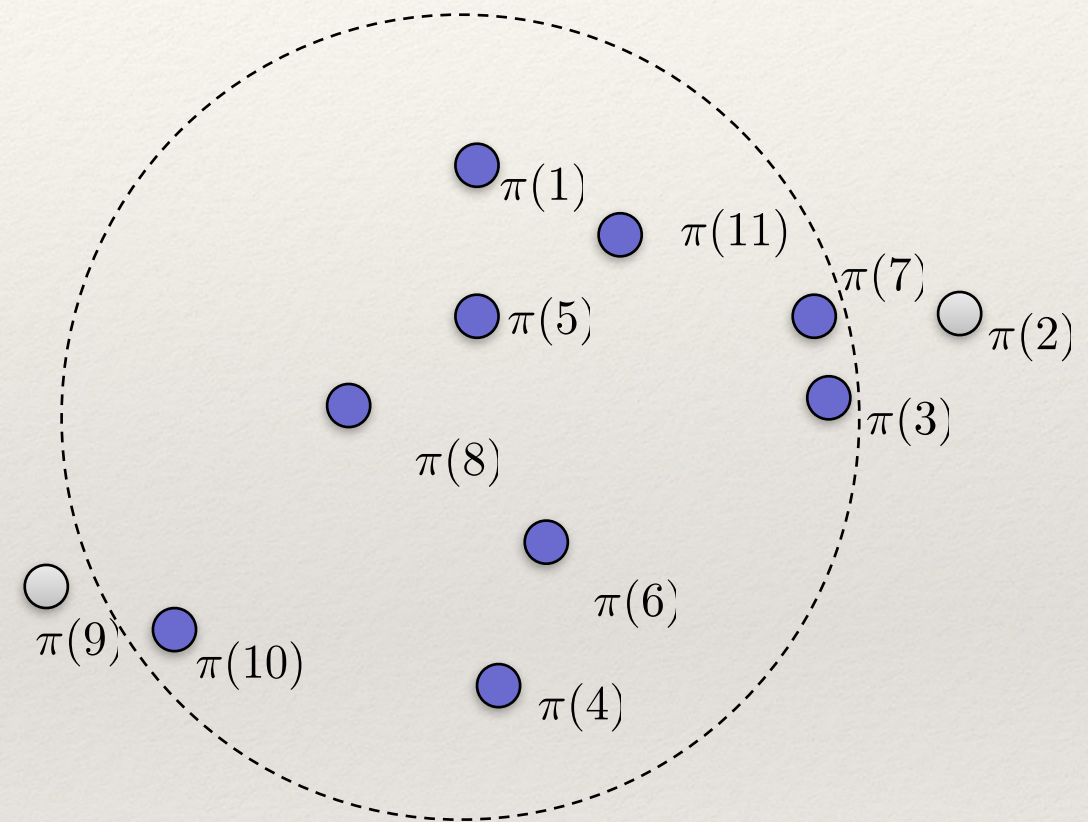
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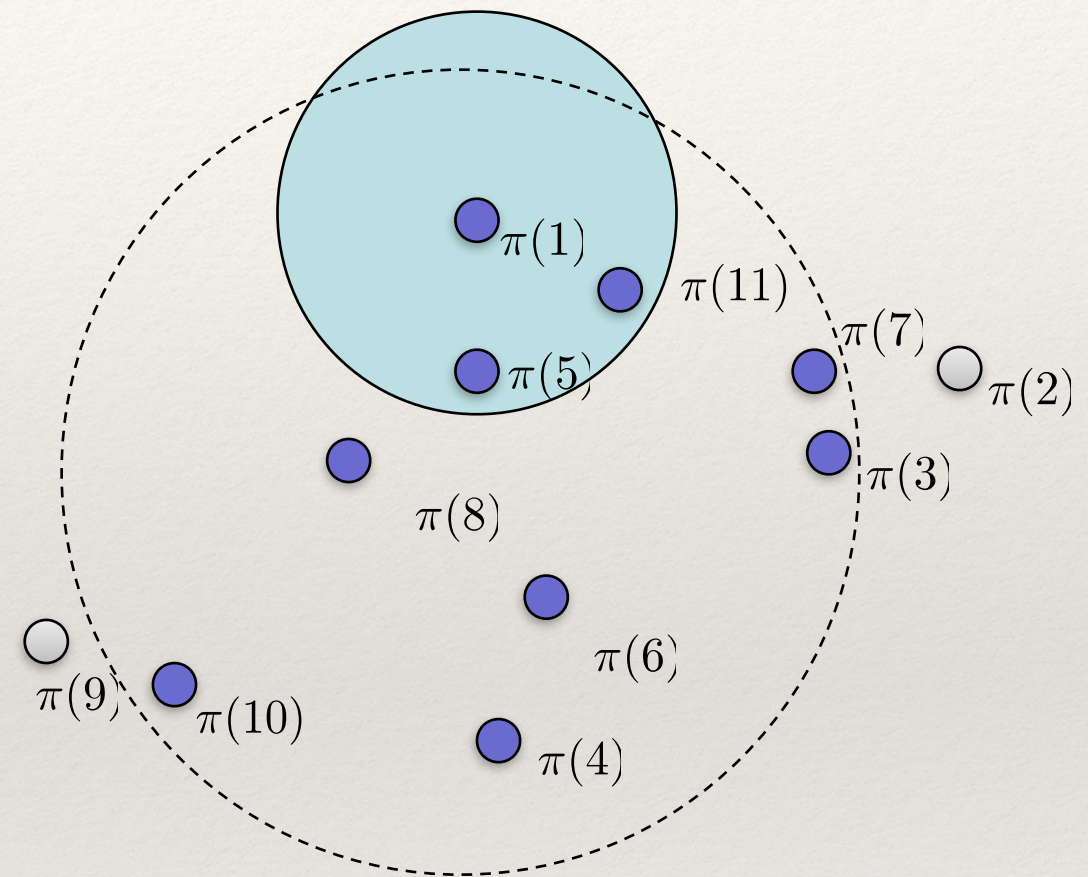
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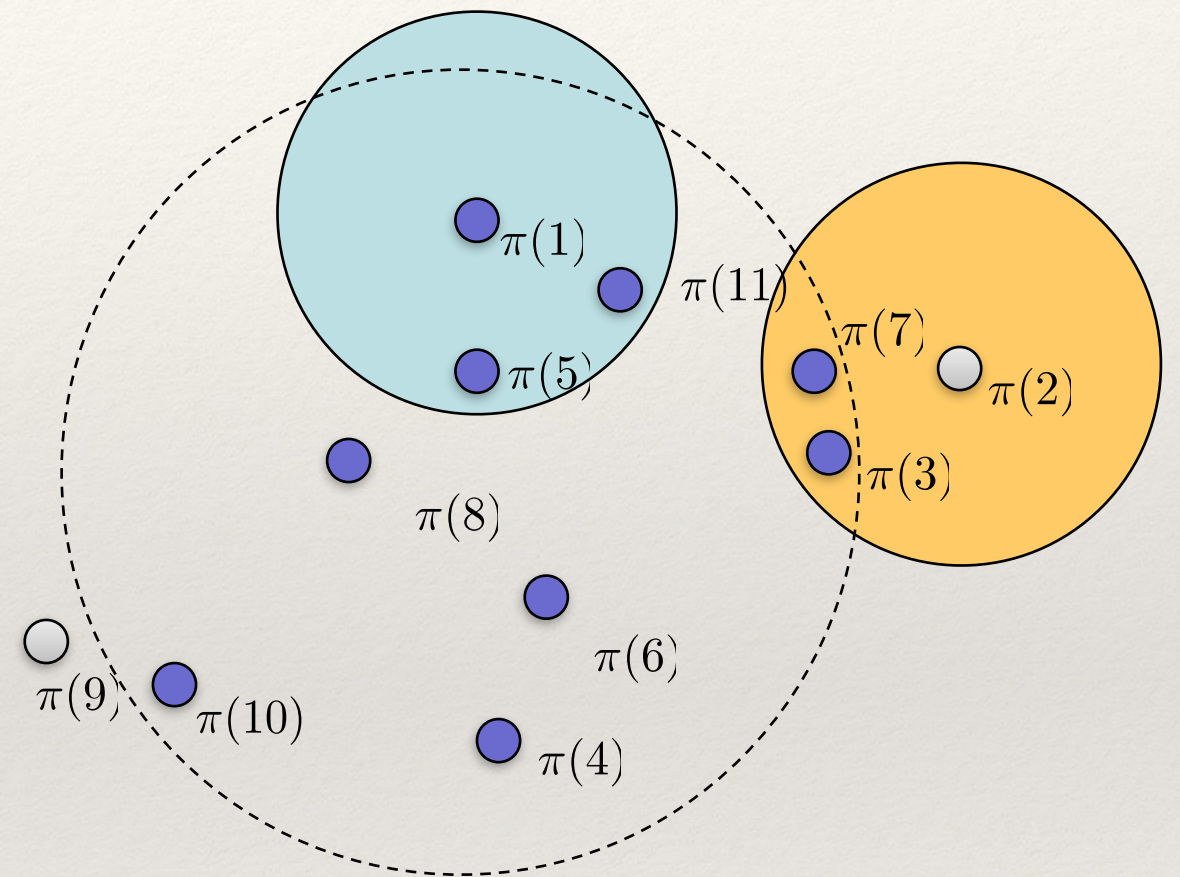
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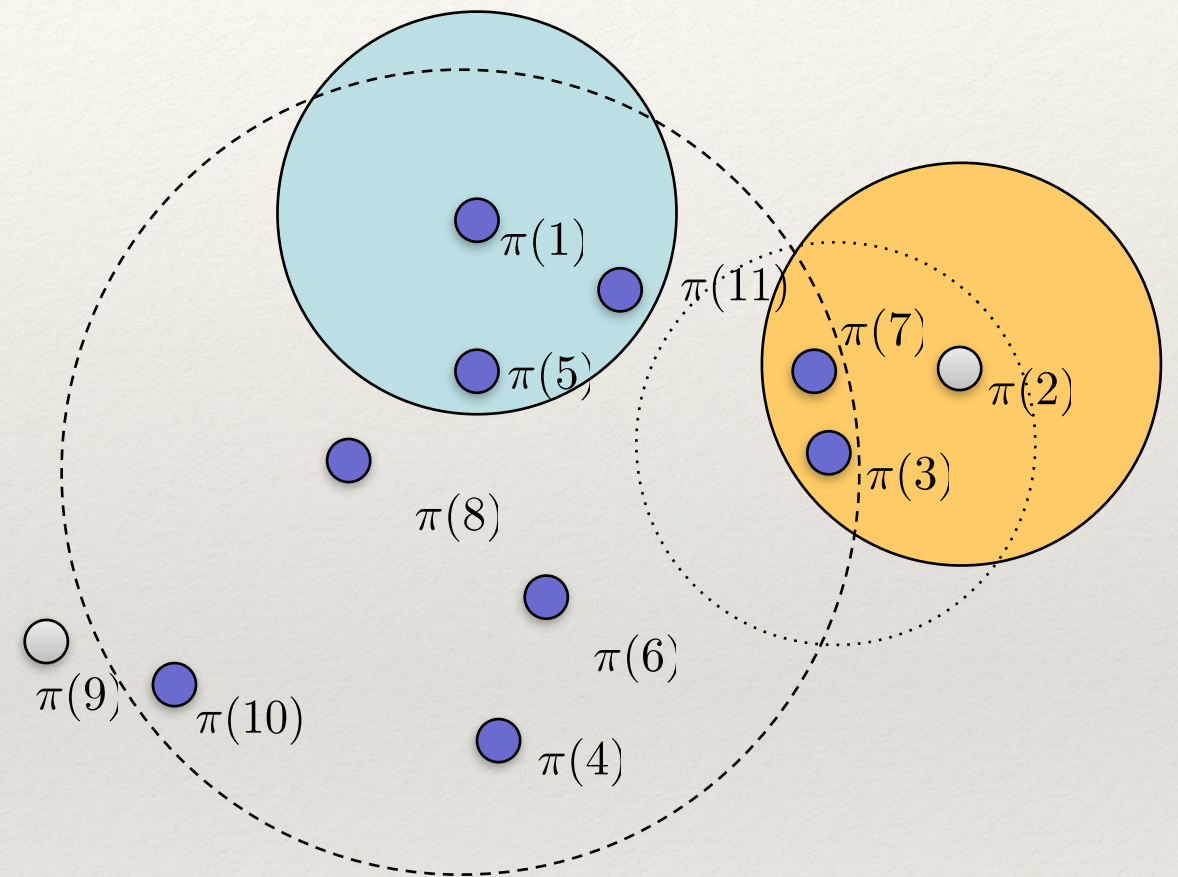
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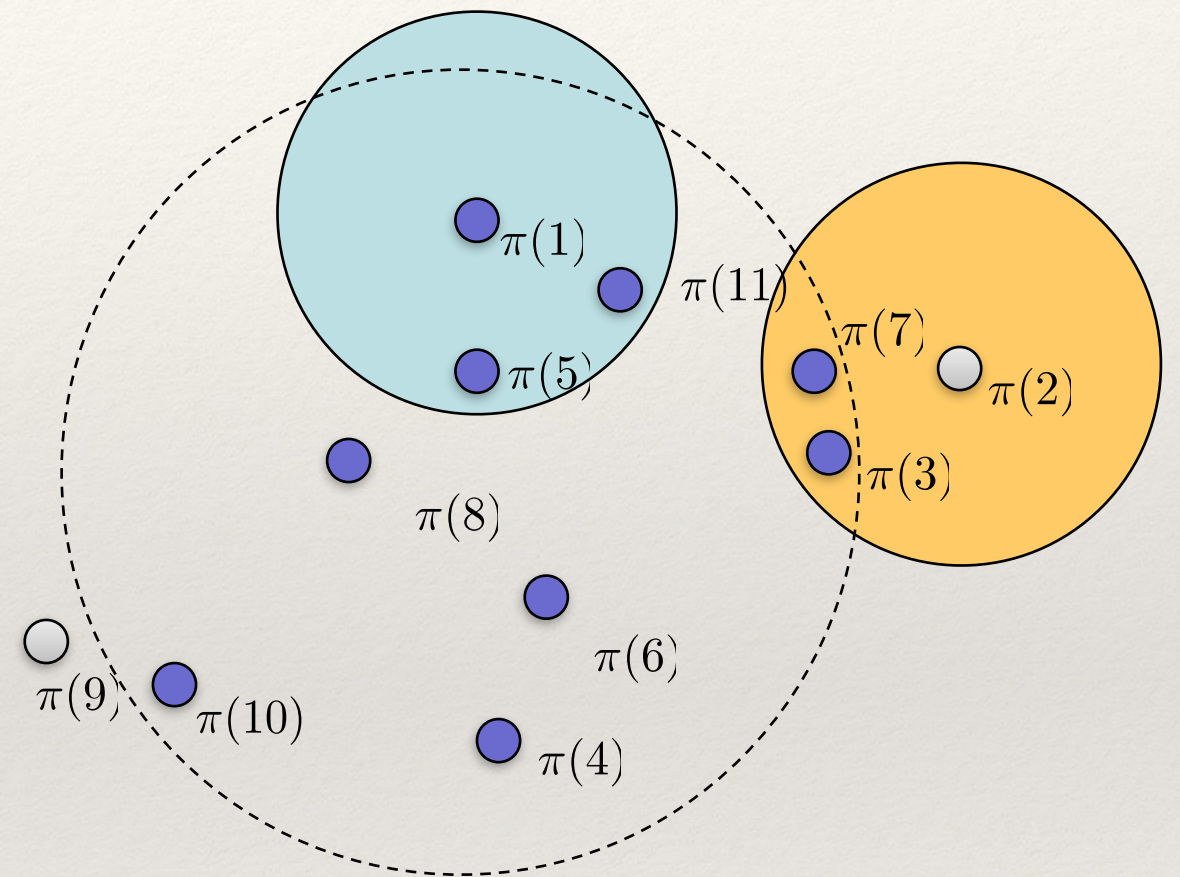
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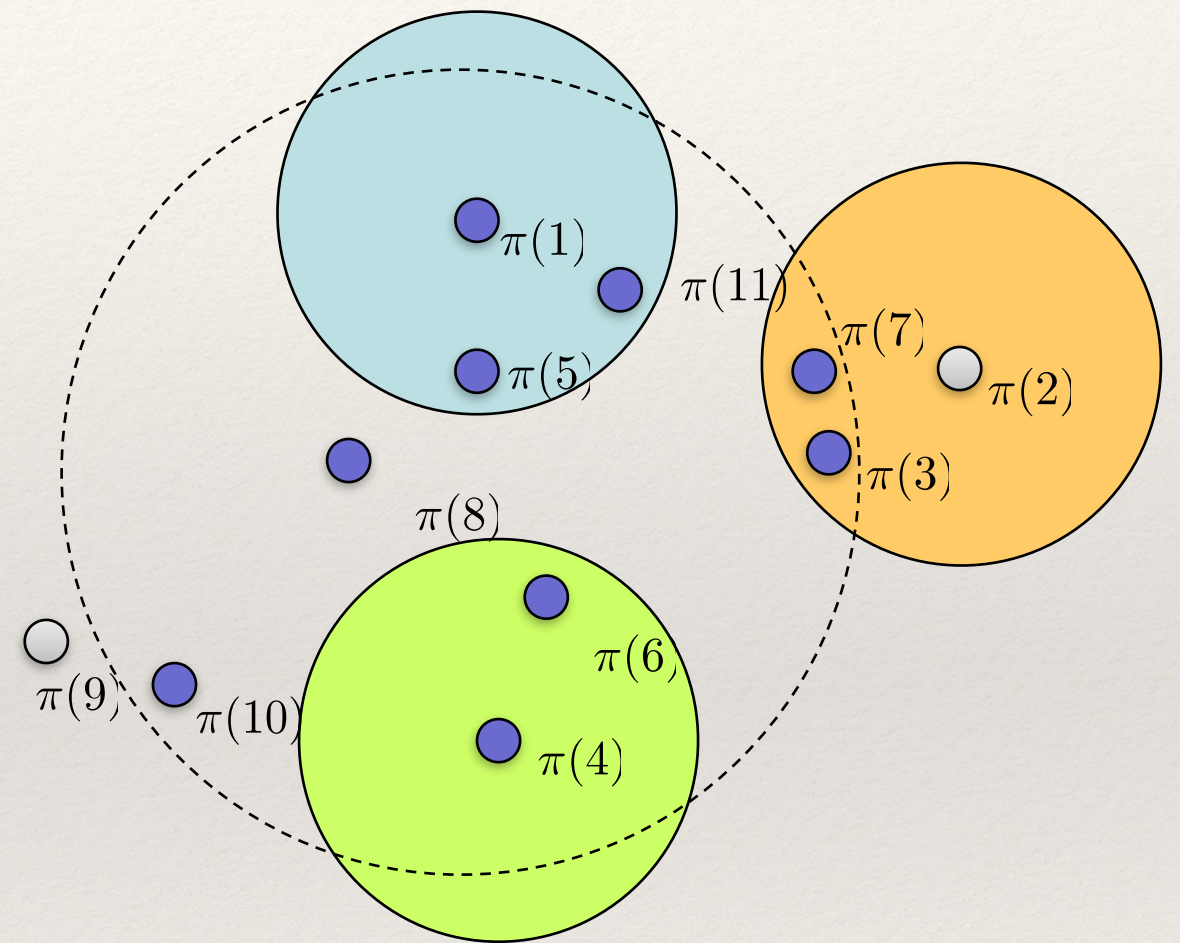
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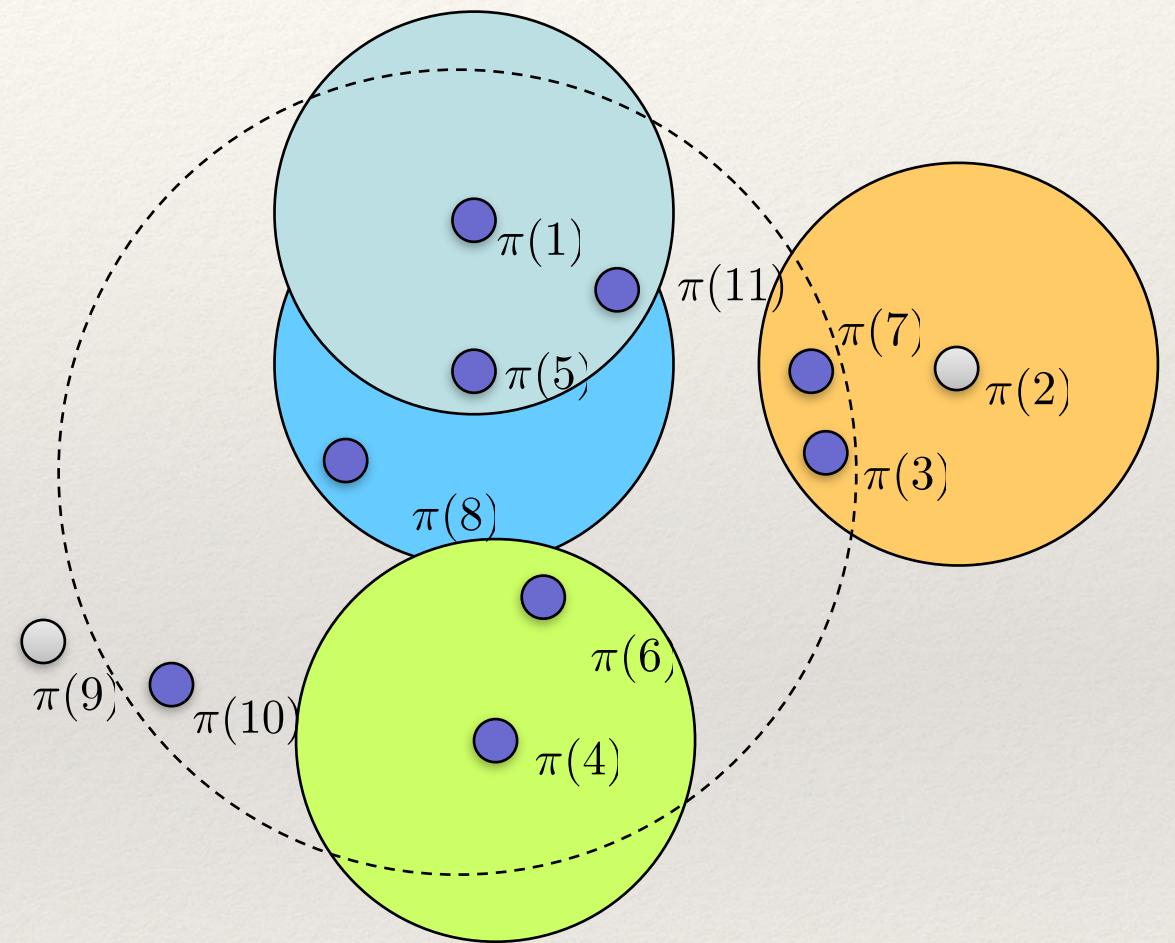
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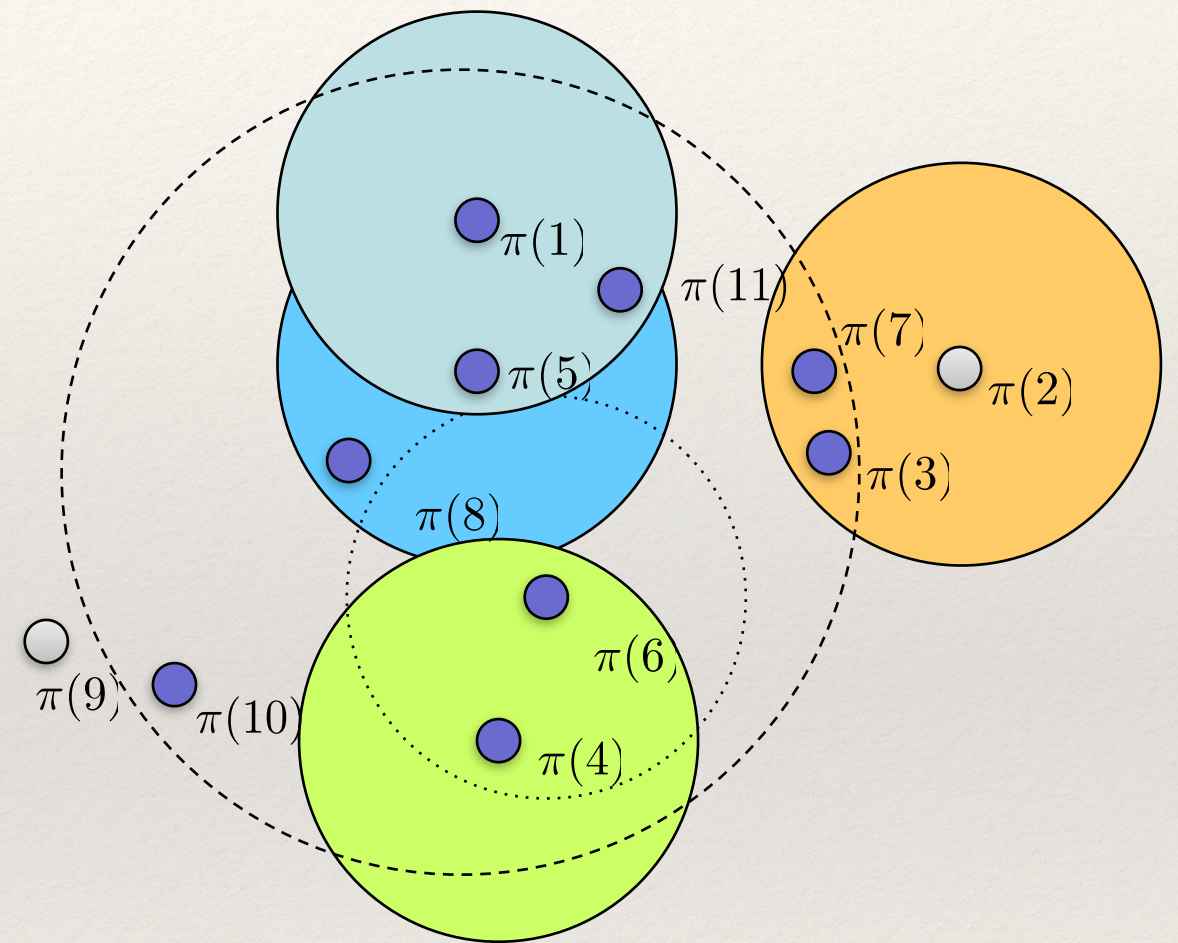
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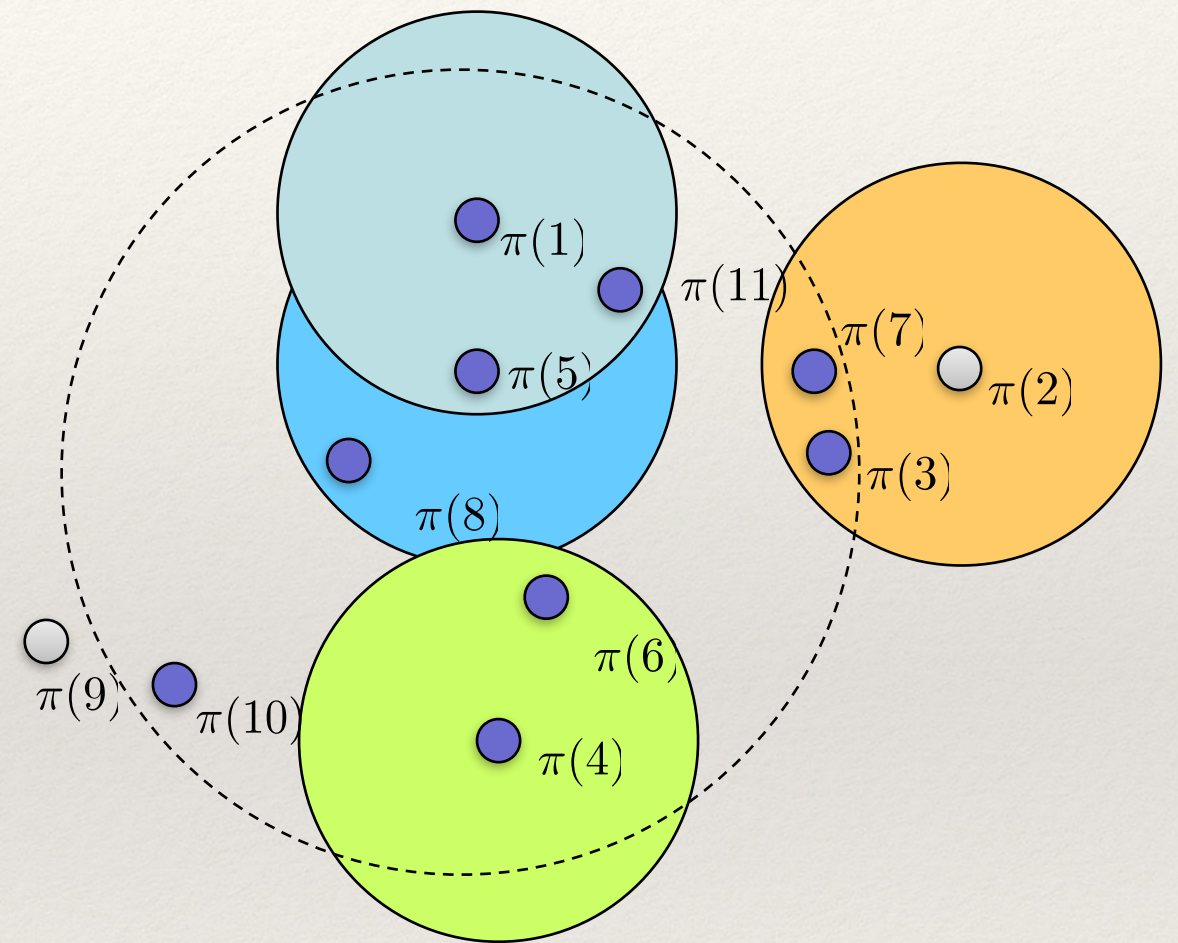
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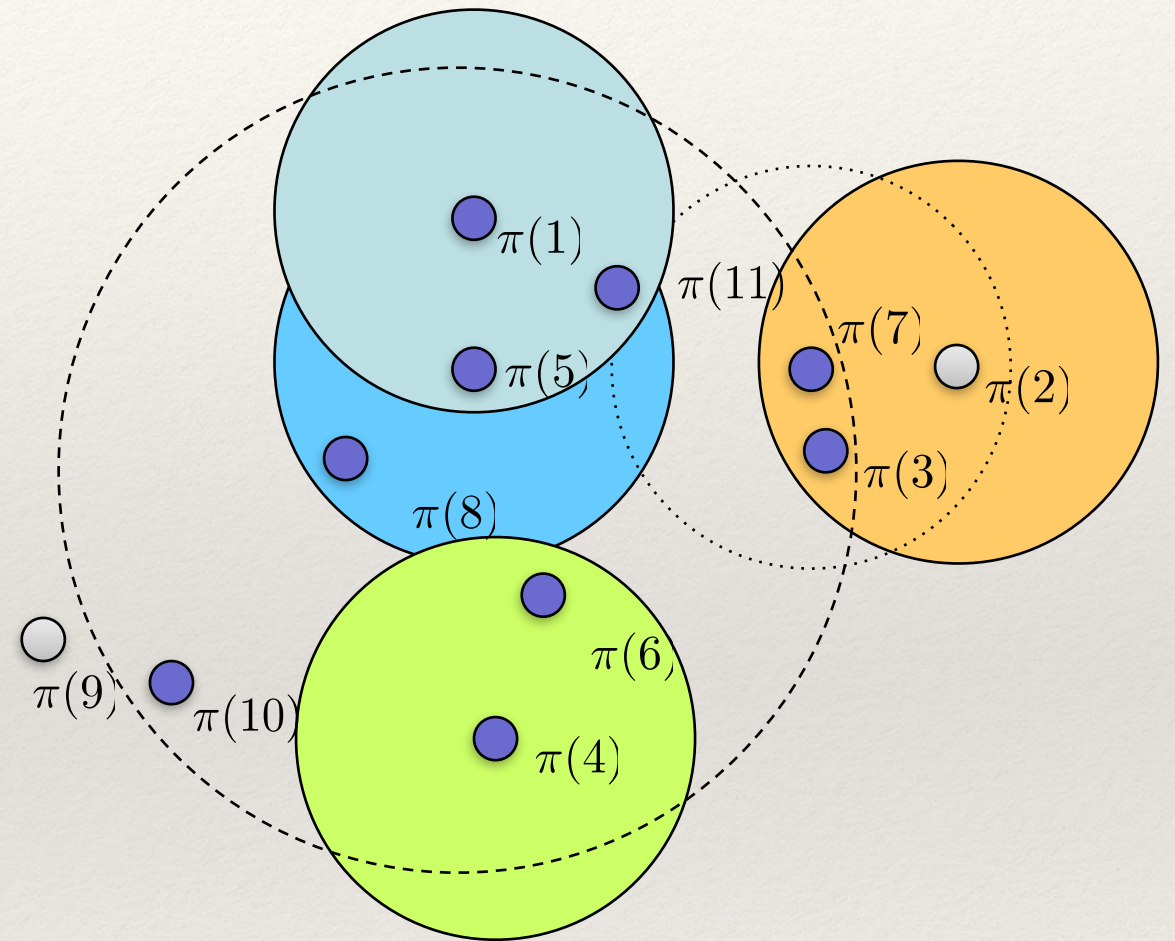
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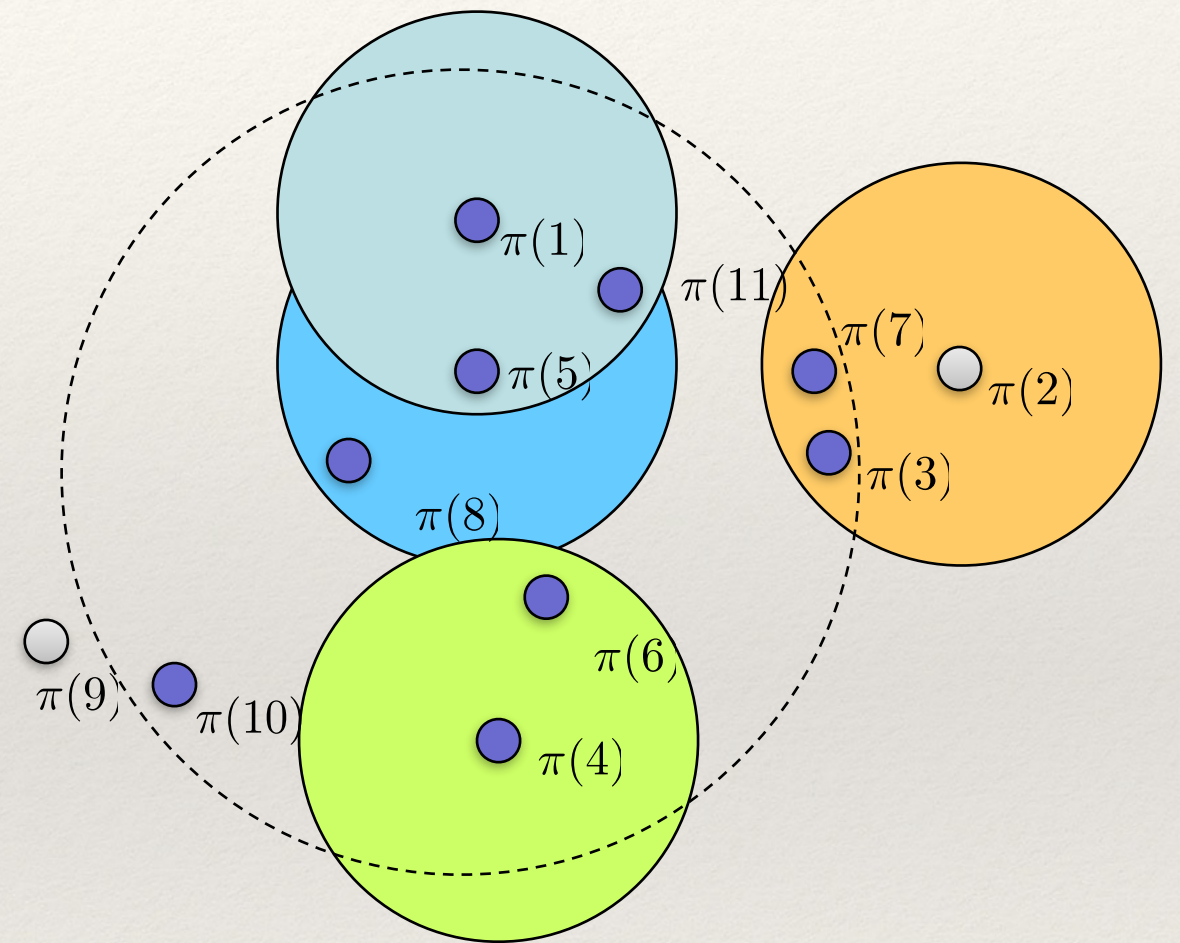
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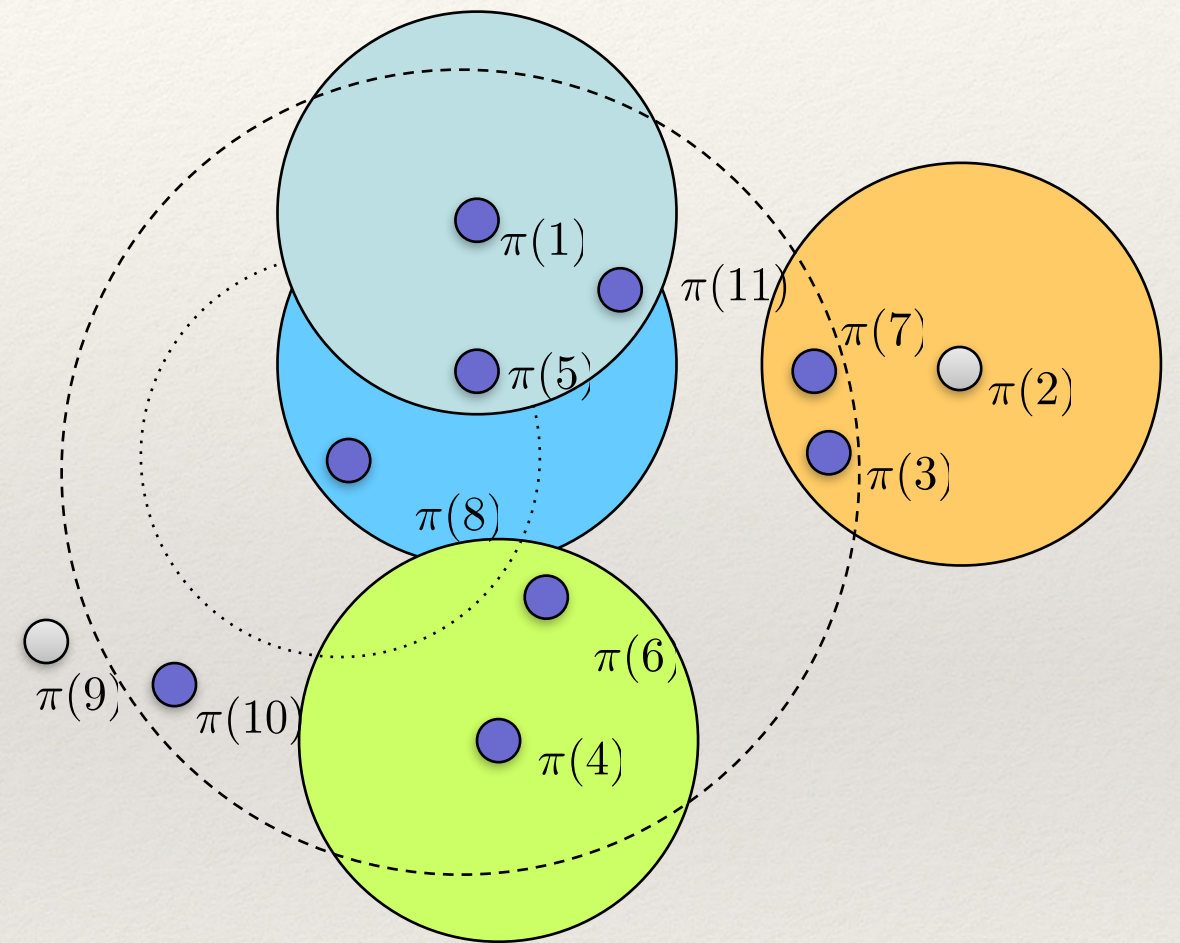
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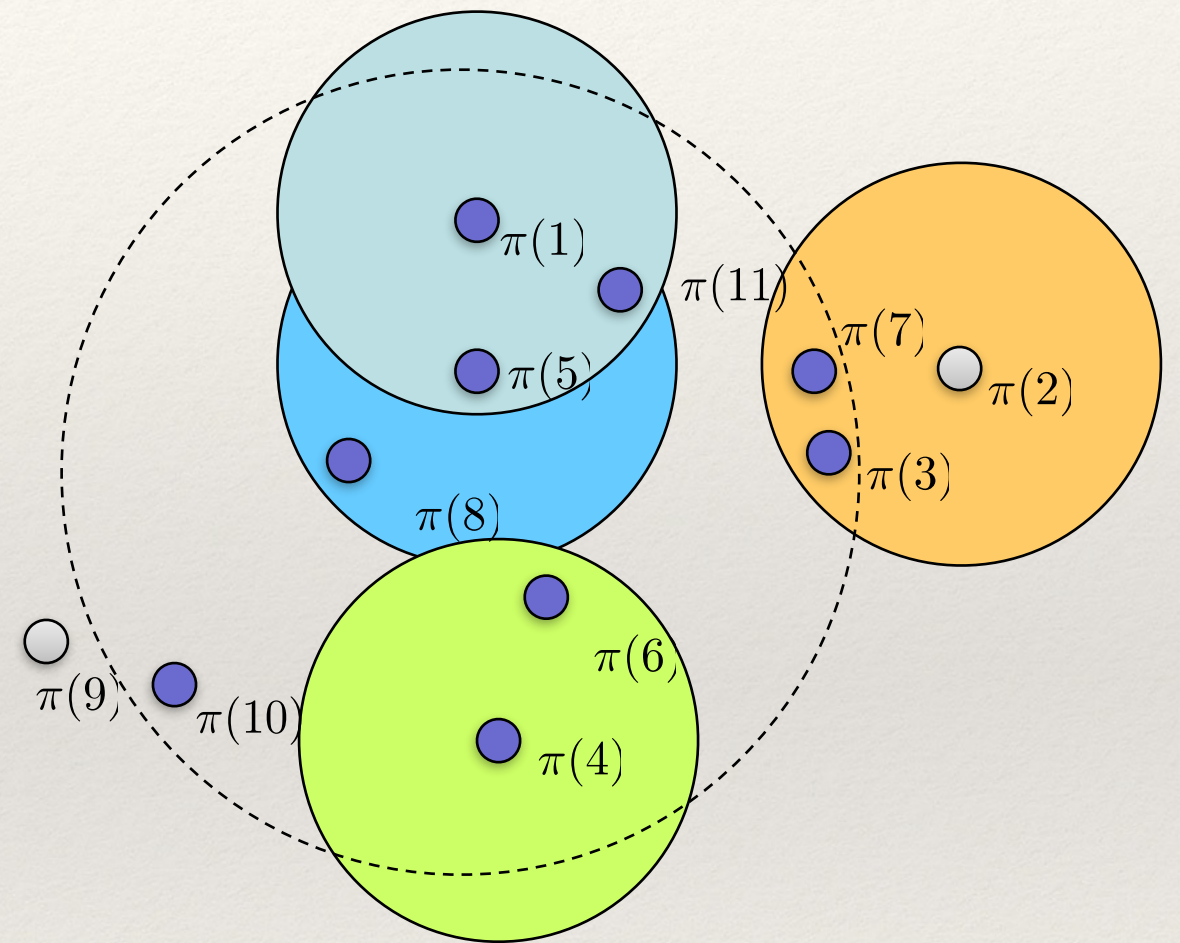
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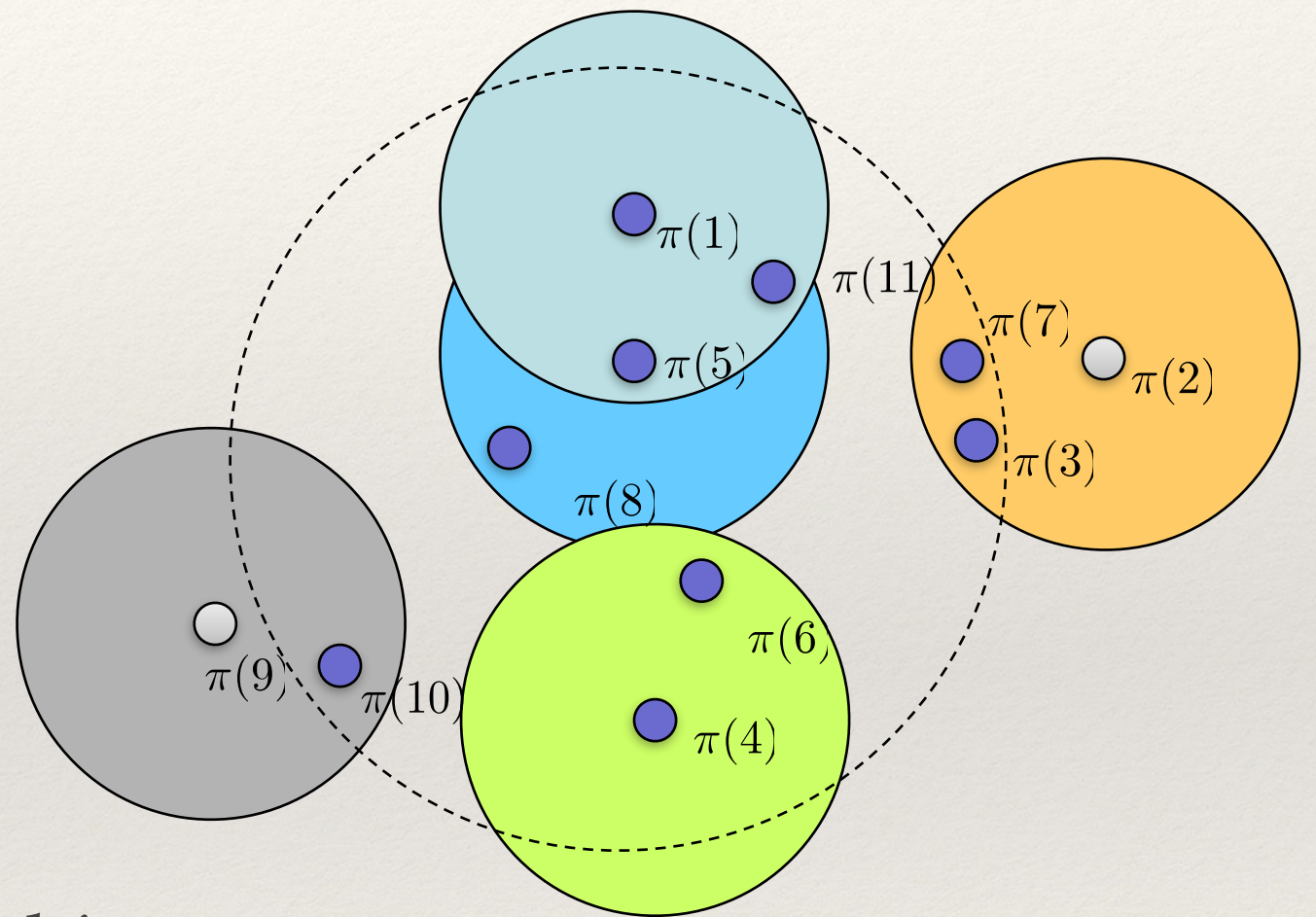
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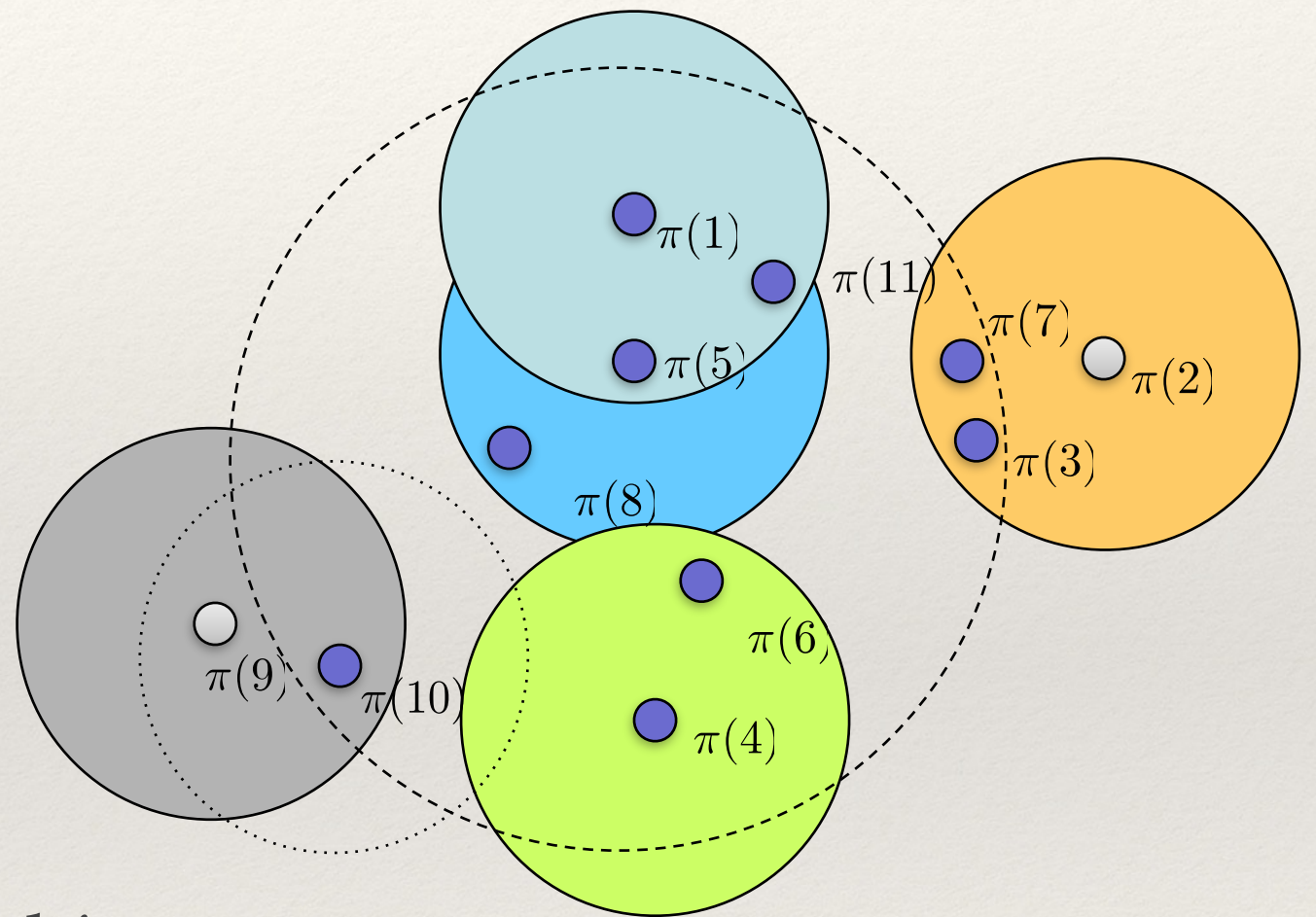
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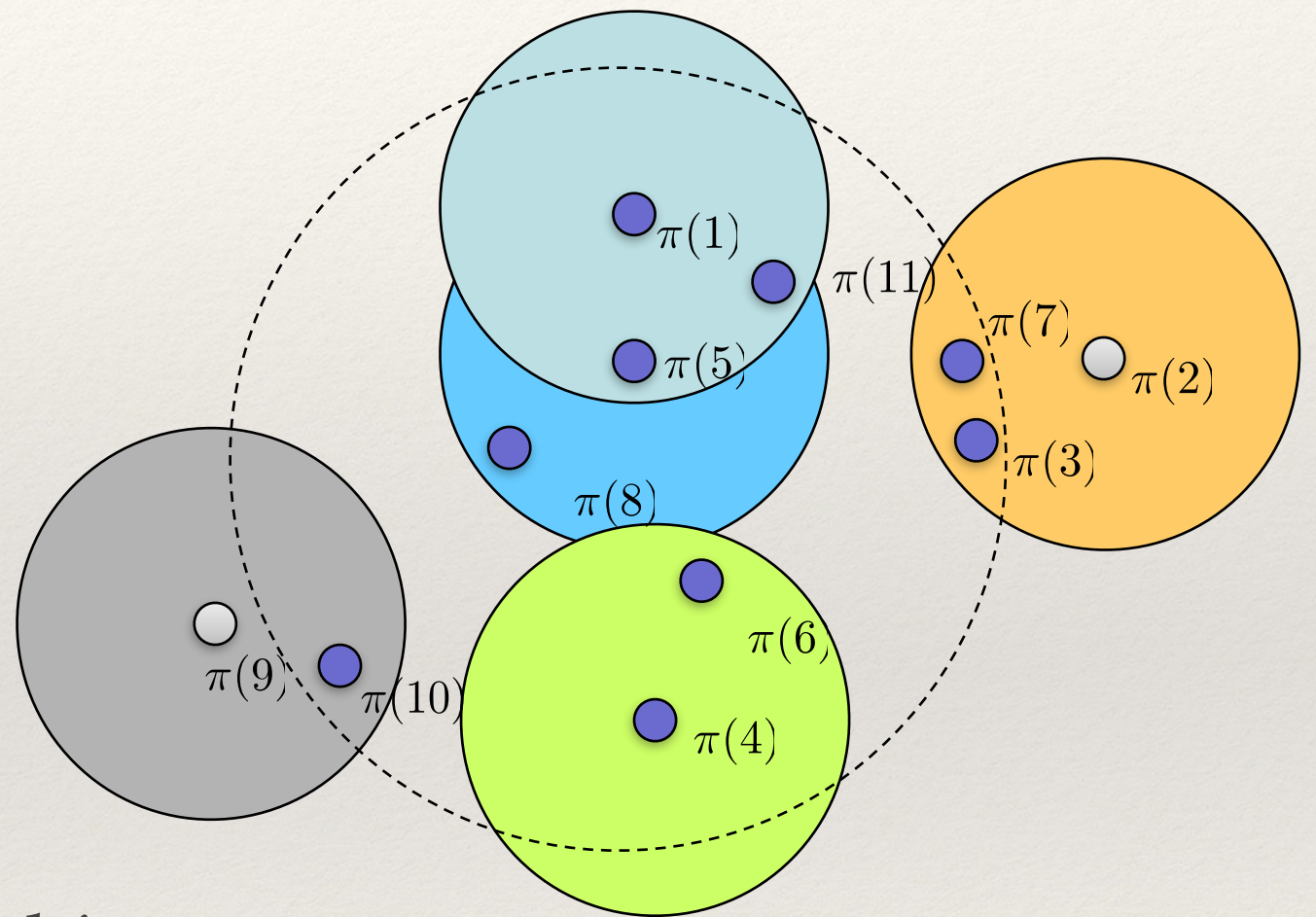
Partitioning of a single set

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Partitioning of S on level $i+1$:

for $j = 1, \dots, n$

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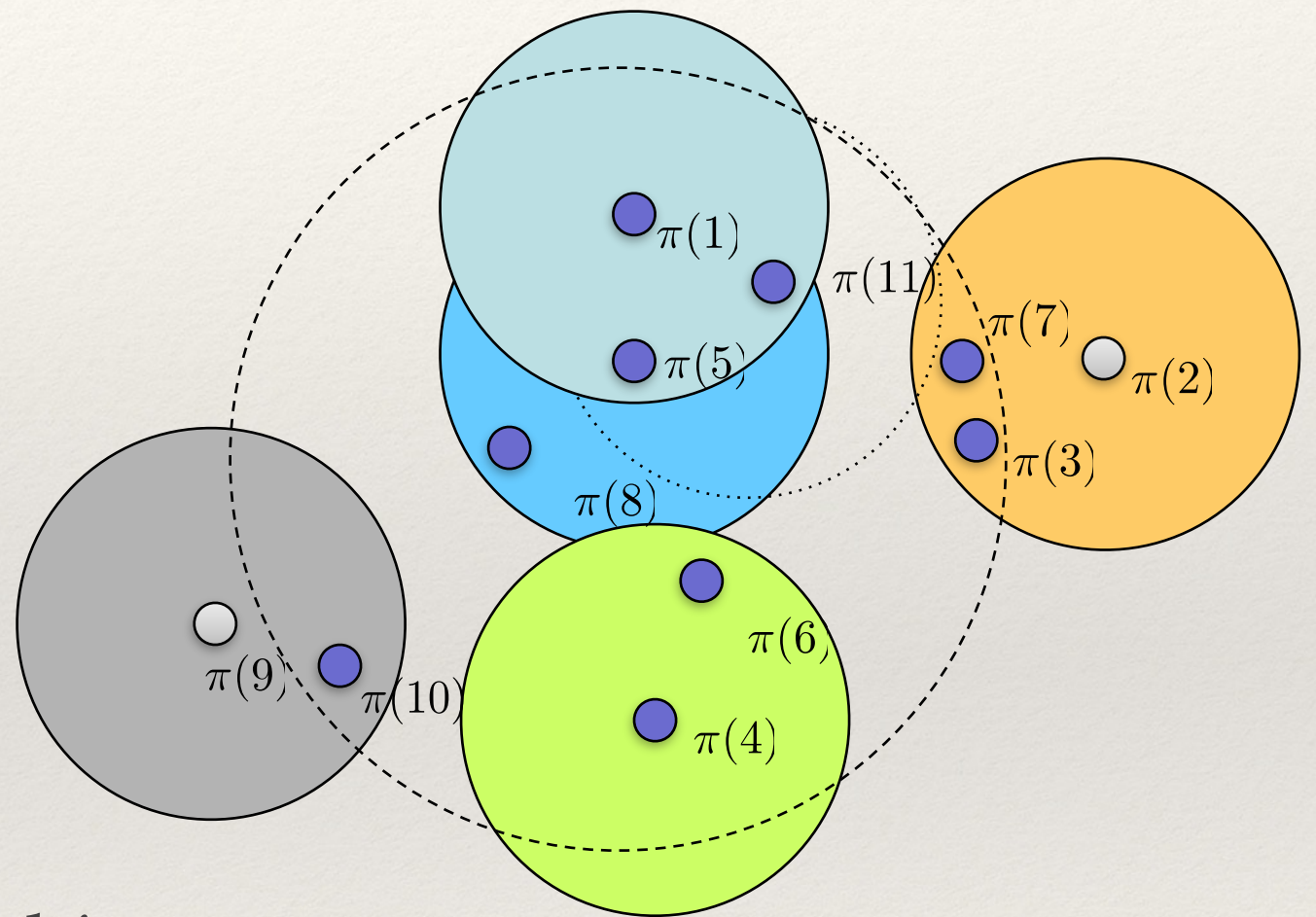
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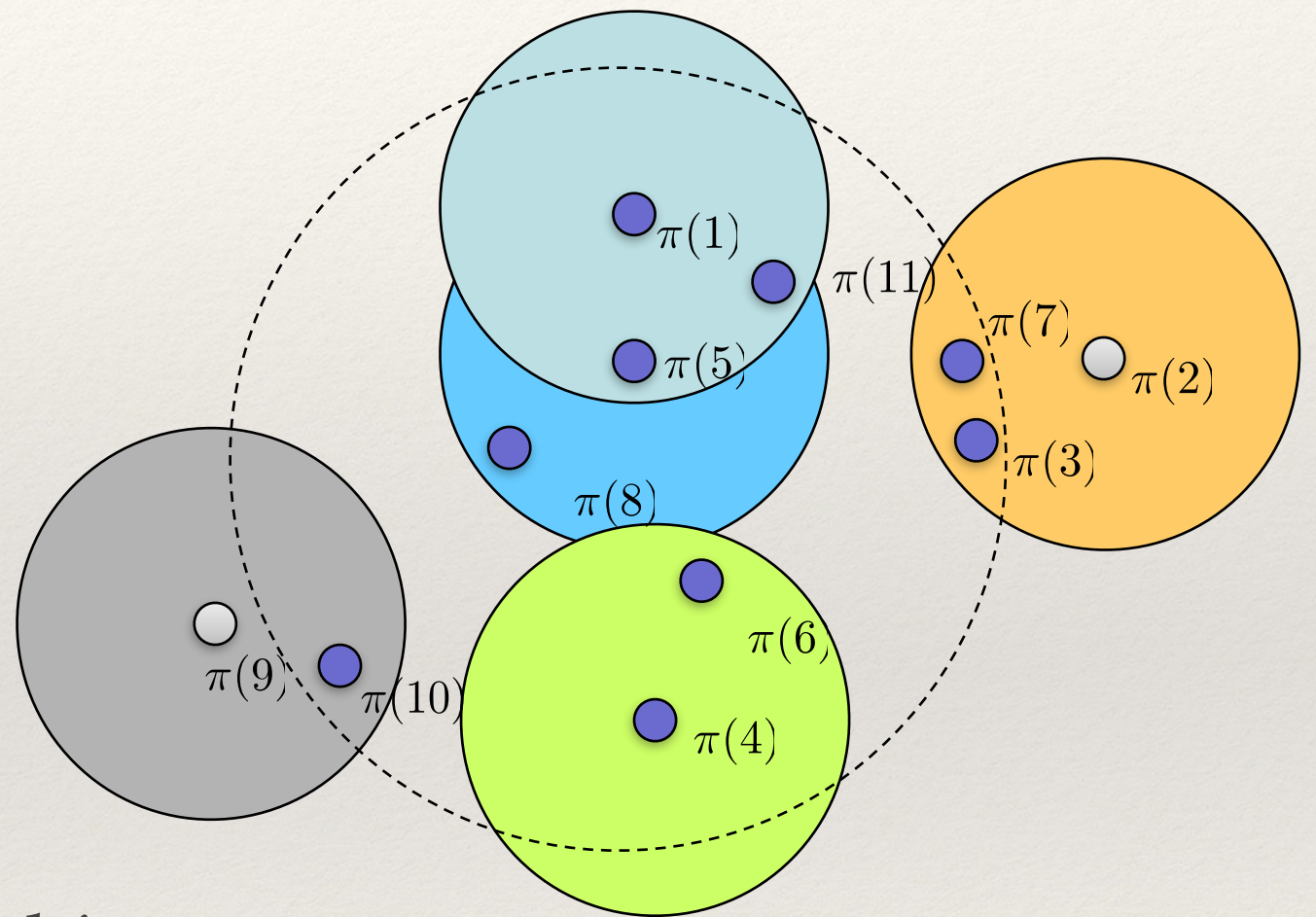
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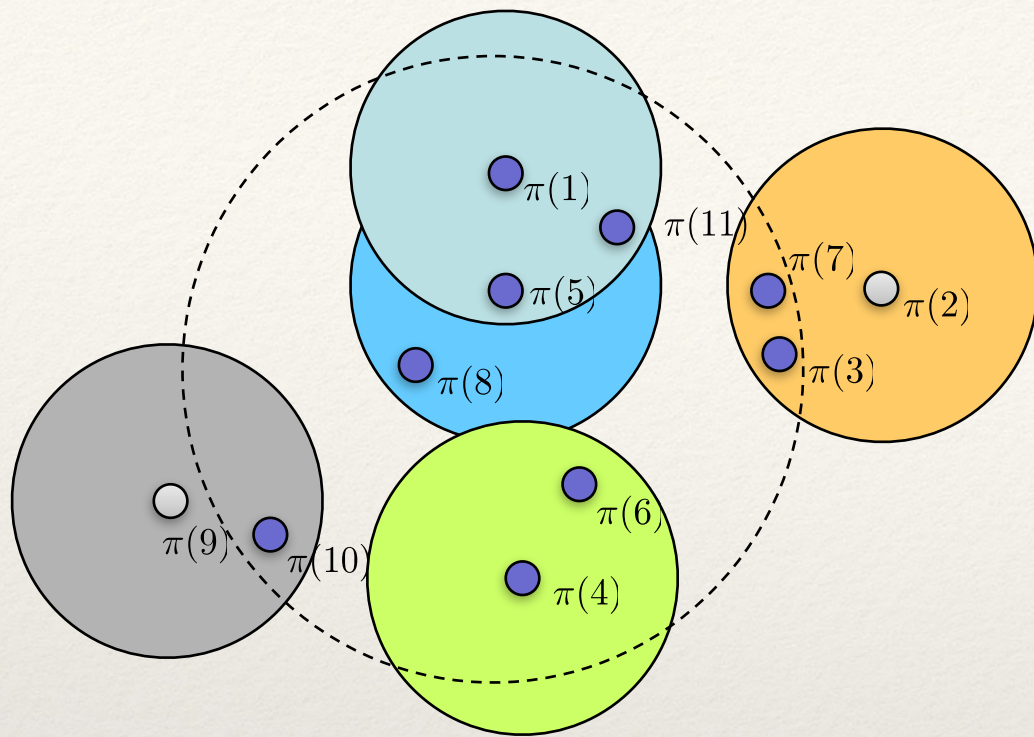
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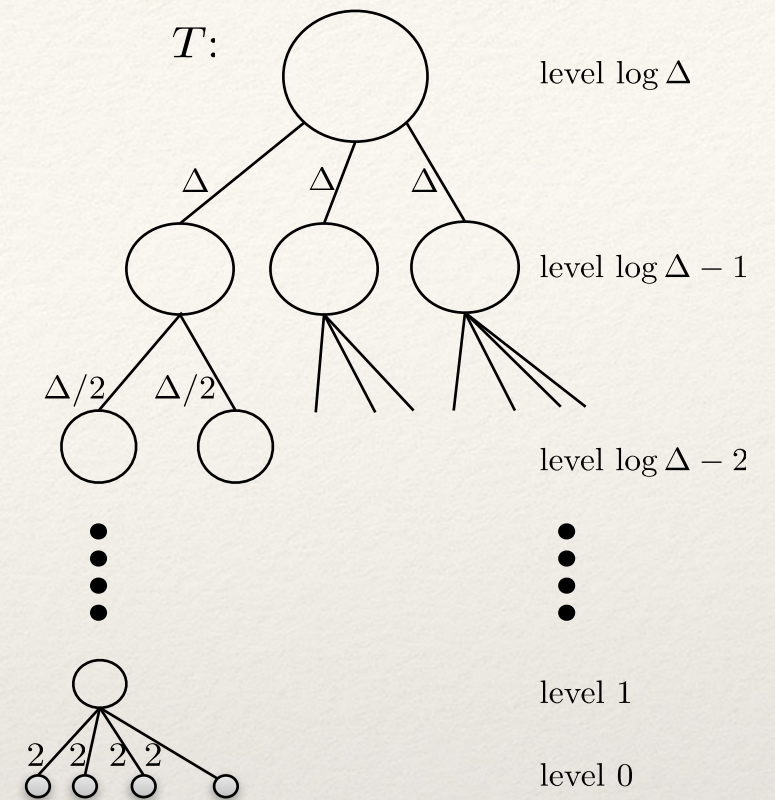


Bounding distances in tree (1)

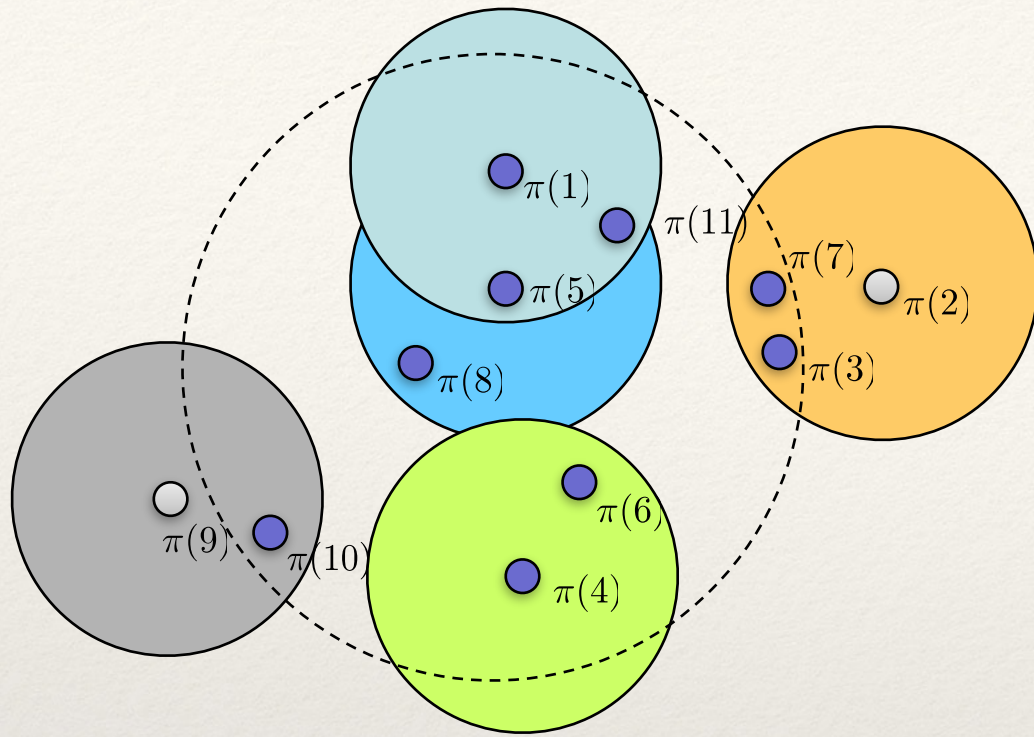


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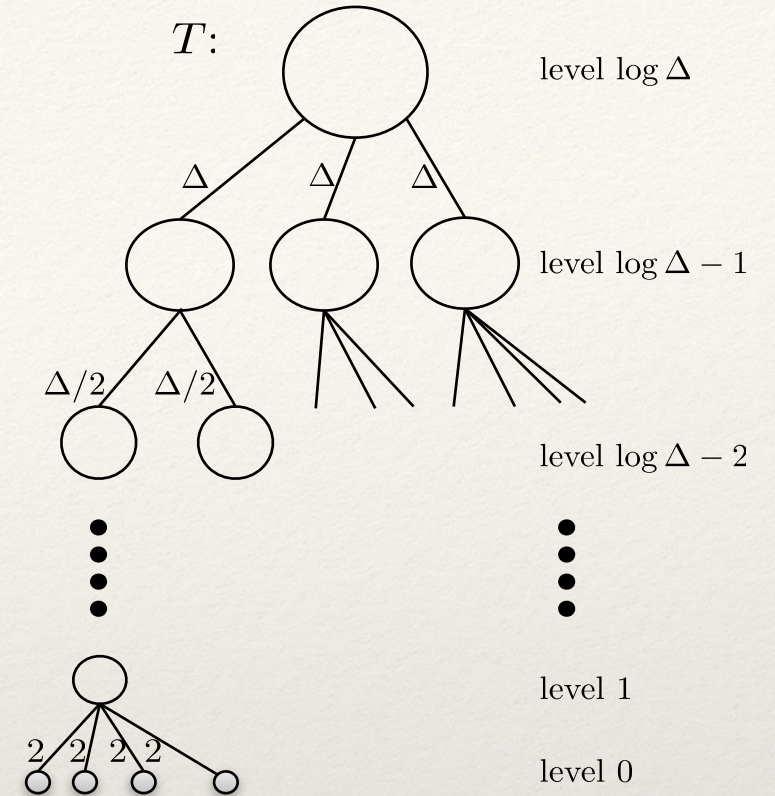


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Lemma 2. $\mathbf{E}[T_{u,v}] \leq \sum_{i=0}^{\log \Delta - 1} \sum_{w \in V} \Pr \left[\text{Sep}_i^A(w) \wedge \text{Sep}_i^B(w) \right] \cdot 2^{i+3}$

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Bounding distances in tree (2)

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$$\mathbf{E}[T_{u,v}] \leq 16 \cdot H_n \cdot d_{u,v} = O(\log n) \cdot d_{u,v}$$

Thank you for you attention!
